



Geosys Reality Capture Solution

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Expert Review Panel / Co-Founder

Geosys Reality Capture Solution 2020

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About Geosys Hong Kong Ltd / 香港吉歐系統有限公司



Geosys Hong Kong Limited (Geosys) was founded in 2009 in Hong Kong, and it is well known as a leading innovative geospatial technology research and development company in the Greater Bay Area now. In the past 10 years, Geosys successfully delivered many enterprise GIS systems and advanced 3d surveying solutions to government departments, public and private companies in Hong Kong and China.

Geosys is specialized in enterprise BIM and GIS integrated 3D cloud-based solutions and it is adopted by Planning Department, Urban Renew Authority, Hong Kong International Airport, Civil Engineering and Development Department, Highways Department, Lands Department of HKSAR Government, as well as contractors, consultants such as Arup, AECOM, Buildking, CLP, CIC etc. in Hong Kong, and Huawei (華為), Shenzhen Urban Planning and Land Information Center (深圳市規劃國土房產信息中心), Guangdong Urban & Rural Planning and Design Institute(廣東省城鄉規劃設計院), etc. in Guangdong Province.

Our services include data capturing and modeling like Remote Sensing, Aerial/UAV Photogrammetry, Point Cloud Scanning, Mobile Mapping and professional Services for enterprise BIM+GIS platform system design, development, delivery and support. Geosys has 14 full time professional staff in Hong Kong with at least a Master Degree in Geospatial / IT discipline and professional memberships in Surveying and IT institutions, and around 20 supporting staff in Shenzhen for system development and administration.

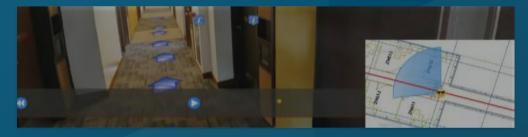
Geosys flagship product, the VR3DTM GIS+BIM Platform System has been a pre-approved Advanced Technology listed in CITF (construction innovation and technology fund) under CIC (Construction Industry Council) since Oct 2018 and it is now widely used in Construction Projects in Hong Kong as a BIM+GIS cloud platform to manage BIM, GIS and 3D Surveying, IoT monitoring data such as Reclamation Data Management System (Contract 3115) of HKIA 3rd Runway, Tung Chung New Town Extension Reclamation Data Management system for BuildKing and AECOM, BIM+GIS+Photogrammetry data management system for Cross Bay Link project for CRBC (中國路橋), etc..





Data Capture from Indoor

Use existing floorplan, as-built BIM models, 720° Panoramic Images, indoor images, 3D Laser scanner, IoT devices, A.I. CCTV Cameras, etc



Industrial Application and Solutions •

Provide Spatial data visualization and analysis functions support to other application platforms by API and Widgets for further smart applications such as Construction Management, Environmental management, Architecture design, City Planning etc.



Capture from the outside

By Aerial photo and LiDAR from UAV and Aircrafts, Videos, Streetview, LiDAR from Vehicles, Government 3D Data, Satellite Images, IoT sensors and Movement Markers, GNSS trackers etc



Common Spatial Data Environment

Use common spatial data standard to import, index and integrate existing world reality data into a common platform for data storage, management, tiling and catching, indexing and data dissemination to different platforms via HTTPs and Steaming APIs

Professional Services for Government and public organizations in Hong Kong



UAV Reality Capture

The latest commercial drone platform by combining intelligence with high performance and unrivaled reliability



Camera Specification





| QTY of Lens | 5 pcs | Material | CNC aluminum alloy |
|-----------------------|-------------------------------|------------------------------------|--------------------|
| Focal Length | 35 mm | Size | 140 x140 x 80 mm |
| Effective Pixels | 24.3MP, total pixels≥120MP | Weight | ≤ 650 g |
| Sensor Size | APS-C (23.5mm x 15.6mm) | Data Reading | USB3.0 Type-C |
| Lens Angle | 45 degree | Data Preprocessing | SHARE Data Manager |
| Exposure Interval | ≥0.8 s | Real-time Image Transmission | PSDK Supported |
| Storage | 1280 GB | Real-time Kinematic | Supported |
| Power Supply | SkyPort / J30J | Intelligent Temperature Control | Supported |
| Power On / Off | Auto On / Off | OLED | Supported |
| Operating Temperature | -10°C~50°C | One Key Reset / Repaire | Supported |
| Humidity | 95% | Firmware Upgraded | Upgrade online |
| 12 geosys.org | | | GeoSys.org |

BST – Certificate of Compliance









General deliverables for the aerial reality model capture

- Take Raw Aerial Images with at least 24.3MP Resolution with fixed distance of each location in flight path in JPEG format
 - Raw image must be taken with APS-C Sensor and 35mm Focal Length lens
 - Take Aerial Images in different 5 angles, one in nadir and others in 4 oblique directions with 45 degree.
 - Each image must contain Fixed RTK position with +/- 5 cm accuracy
- Letter of "Permission to Operate Non-Scheduled Service for Hire or Reward UAS" by Civil Aviation Department
- Accuracy report with at least 5 ground check point and RMSE within 10 cm Accuracy in XY and Z direction
- Deliver 3D Point Cloud in LAS (and PLY/E57/XYZ (optional))
- 3D Photo Mesh Reality Model in Open Scene Graph (OSGB) (/3D Tiles/S3M)(optional)
- Digital Surface Model in Geo-Tiff format
- Digital Terrain Model in XYZ/Geo-Tiff format
- Digital True OrthoPhoto in Geo-Tiff / ECW format
- All geospatial data deliver in Hong Kong 1980 grid coordinate system and HKPD



RTK Positioning with Beidou + GPS Support

by Geosys Mount Point Or Lands Department Network RTK Onsite

- RTK GPS locations and Orientation could be written into Images POS for 5 angles
- With the support of Beidou, RTK can be fixed faster than only GPS.
- RTK link to M300 can be more stable than only GPS
- Positioning accuracy will be better using closer reference station.







Permission to Operate Non-Scheduled Service for Hire or Reward UAS

Flight Approval issued from Civil Aviation Department

Application for Operating Unmanned Aircraft System (UAS) Ref: UAS-202007-0012

I refer to the application submitted on 12 July 2020 for the operations of UAS "DJI Mavic 2" or "DJI M300 RTK" scheduled as follows:-

Date:

22 July 2020 - 21 October 2020

Time:

07:00 - 18:00 (local time)

Areas:

1. Hang Kin Street, Ma On Shan

2. Wing Tai Road, Chai Wan

Please find enclosed the Permit for use of aircraft for the provision of air service – Unmanned Aircraft System (UAS). According to Article 48 of the Air Navigation (Hong Kong) Order 1995 (CAP. 448 sub. leg. C), a person shall not recklessly or negligently cause or permit an aircraft to endanger any person or property. You must ensure safety of UAS operations at all times and follow the safety parameters specified in Attachment 1. You are responsible for obtaining all the necessary authorisation or permission from other Government Departments, and complying with conditions required by them, before operating the UAS.

Yours sincerely,

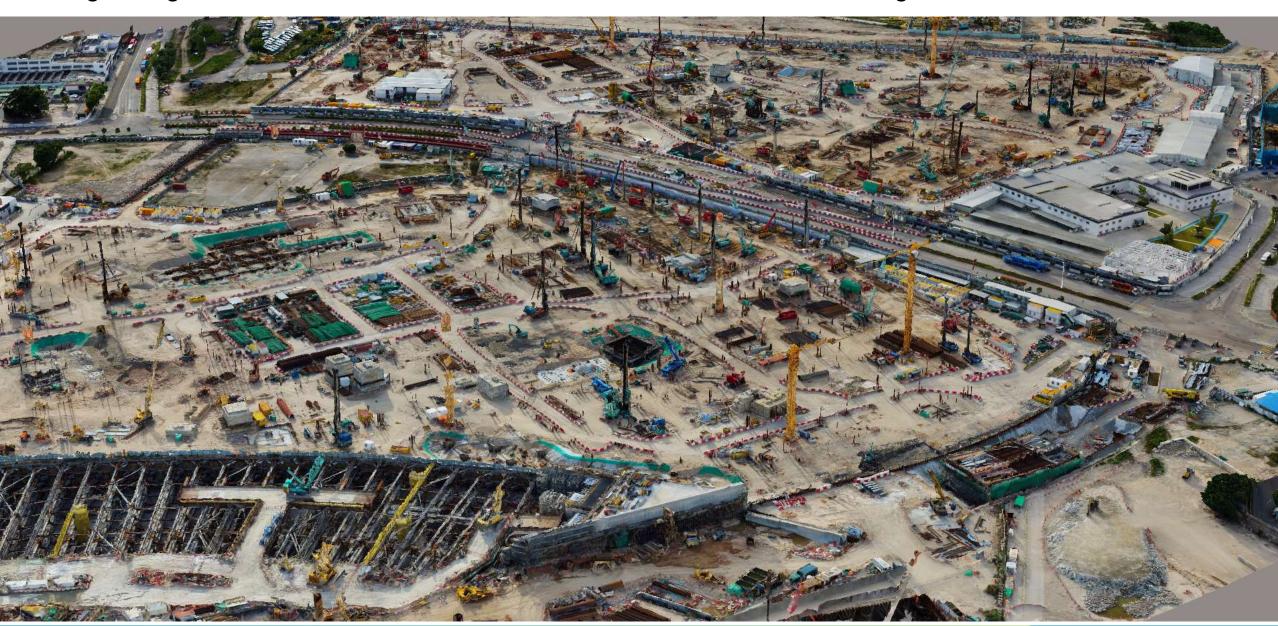
(Harry AU)

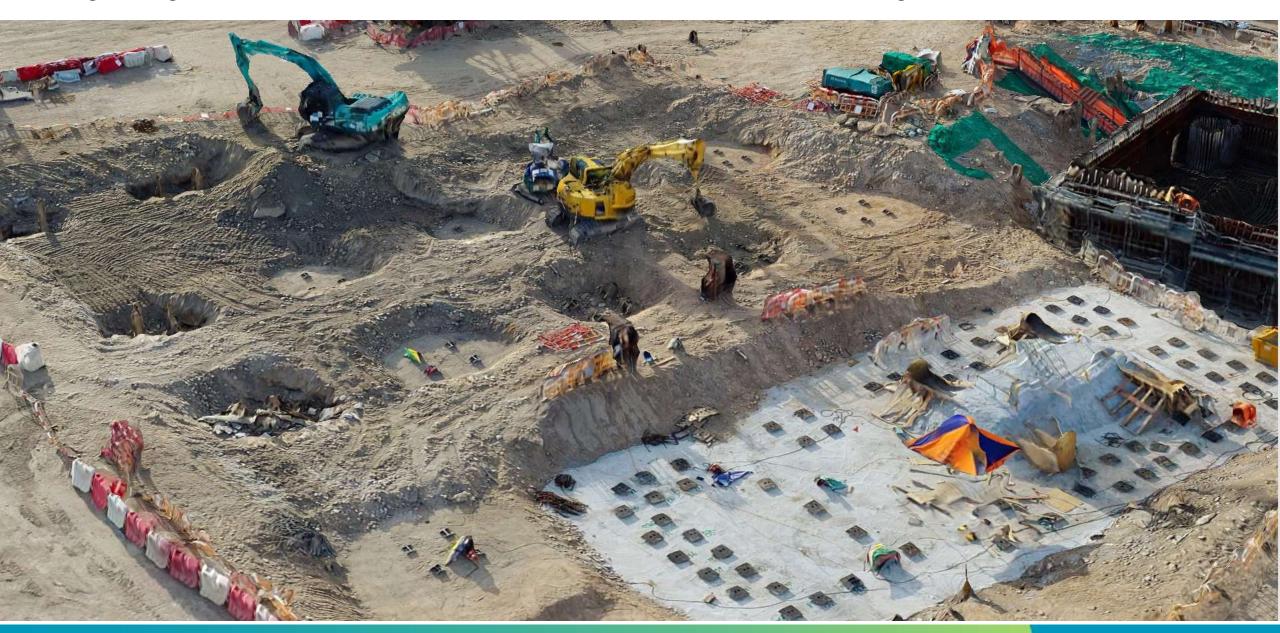
for Director-General of Civil Aviation

Encl. (2)





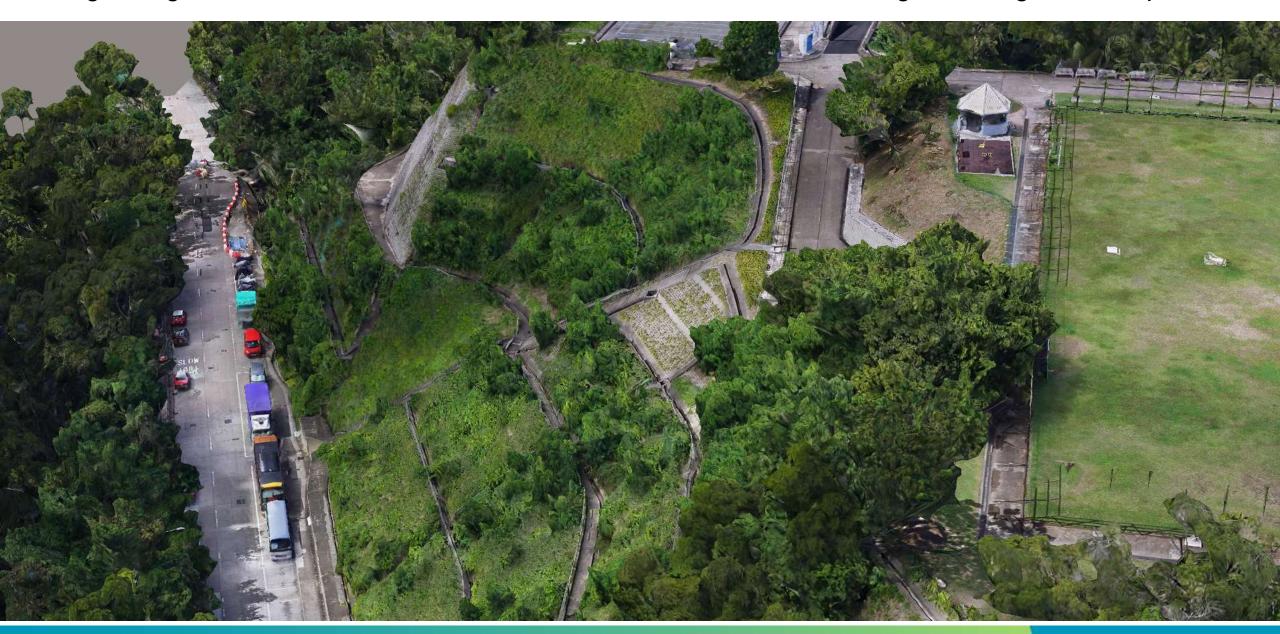


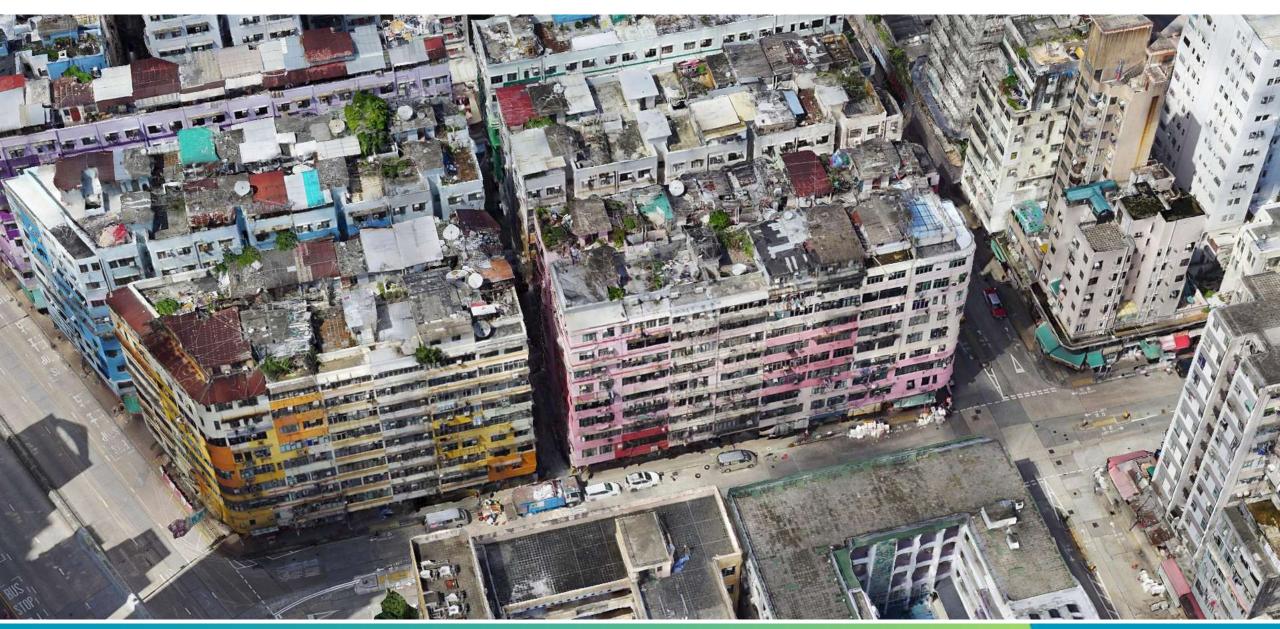




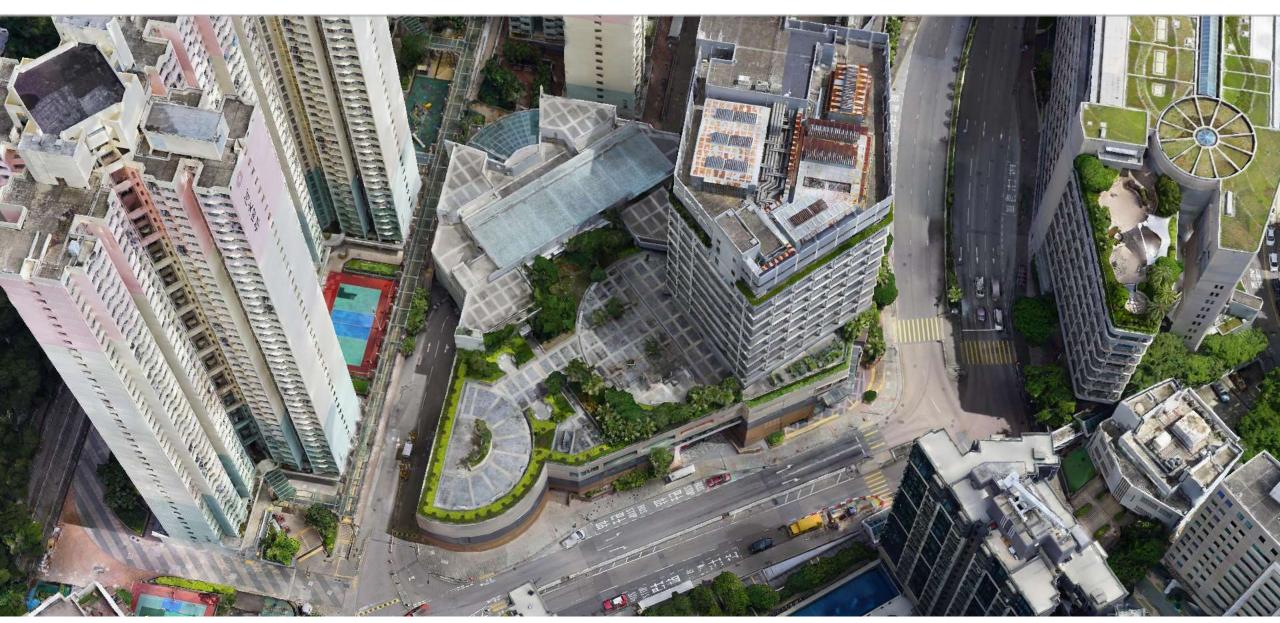














UAV LiDAR System



Features

- Light-weighted for Drone LiDAR Collection Applications
- High Quality LiDAR Sensor with Livox Mid-40
- High Resolution LiDAR Measurement Data with 100,000 Points per Second
- High Performance POS/NAV for Centimeter-level Accuracy



| Specifications | | |
|-----------------------------|-----------------------------------|--|
| Laser Sensor | Livox Mid-40 | |
| Range Accuracy | ± 2 cm | |
| | 90 m @ 10% reflectance | |
| Scan Range | 130 m @ 20% reflectance | |
| | 260 m @ 80% reflectance | |
| System Accuracy | ± 5 cm | |
| DOC 6 - 1 D - 1 | Attitude: 0.008° (1σ) | |
| POS System Performance | Azimuth: 0.038° (1σ) | |
| Onboard Storage | 128 GB | |
| Ports Available | Ethernet | |
| Weight (excl. battery) | 1.0 kg | |
| Dimensions (Main Unit) | 125*70*116 mm | |
| Route Planning Software | LiPlan (proprietary) | |
| Acquisition/PP POS Software | LiAcquire web & LiGeoreference | |
| Field of View | 38.4° | |
| Scan Rate | 100,000 pts/s | |

General deliverables for the aerial laser scanning

- Capture LiDAR Point Cloud data by UAV Laser Scanner
 - Laser Scanner System Range Measure Accuracy within +/- 5 cm
 - POS system integrates RTK GNSS and High Accuracy IMU system
 - Point Cloud has at least 3 returns
- Point Classification with at least 6 classes : Ground, High/Medium/Low Vegetation, Building, Model Key Point, etc
- Letter of "Permission to Operate Non-Scheduled Service for Hire or Reward UAS" by Civil Aviation Department
- Deliver 3D Point Cloud in LAS (and PLY/E57/XYZ (optional))
- Topographic map in Shp/CAD format
- Digital Surface Model in Geo-Tiff format
- Digital Terrain Model in XYZ/Geo-Tiff format
- All geospatial data deliver in Hong Kong 1980 grid coordinate system and HKPD



UAV LiDAR flight at Kai Tak Sport Park

Flight height: 90m

Flight speed: 3m/s

• Flight time: 21:30~22:50 PM

• Point Cloud Density: 200~500

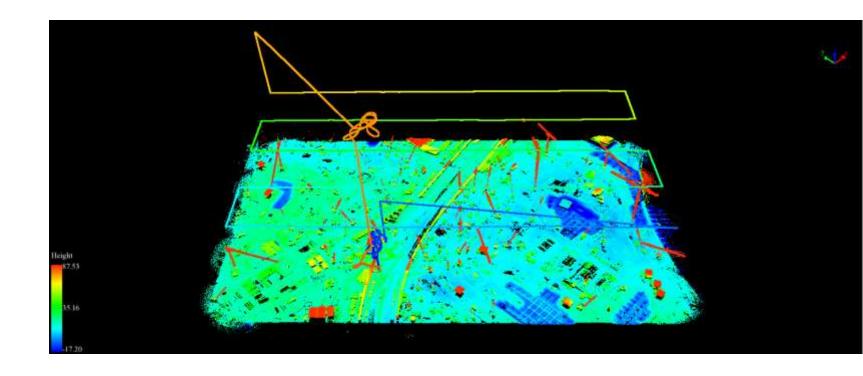
points/sqm

Point Cloud Thickness: 5~10 cm

Point Cloud Accuracy: 5~10 cm

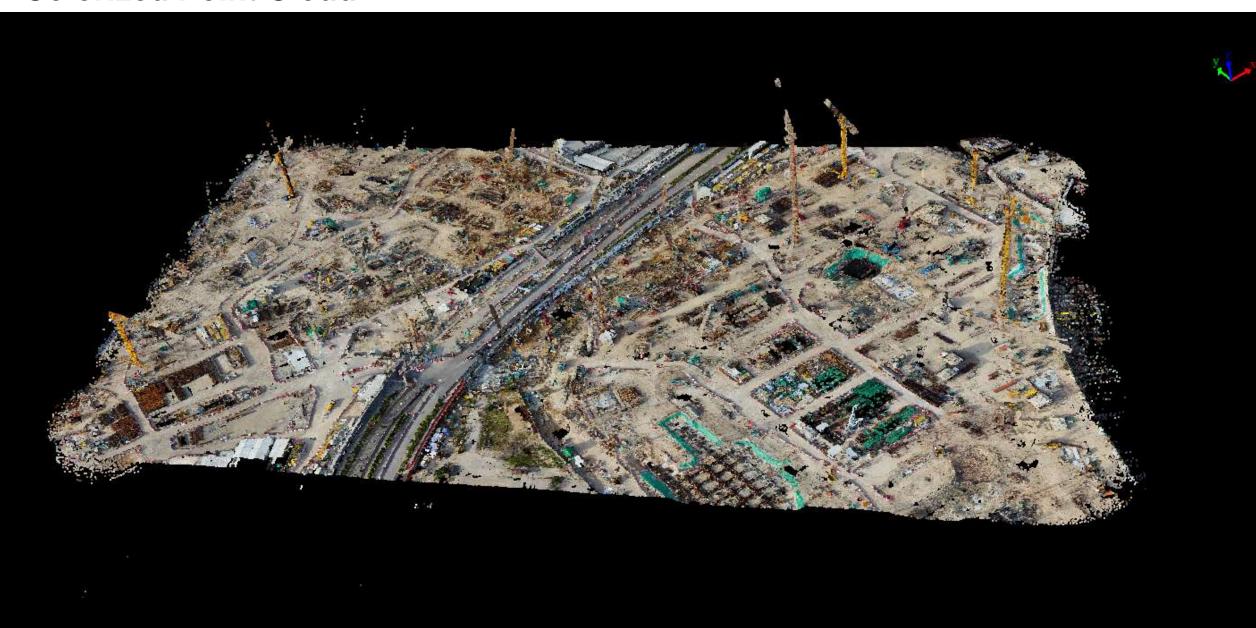
Number of Returns: 3

Flight mode : Manual + Route

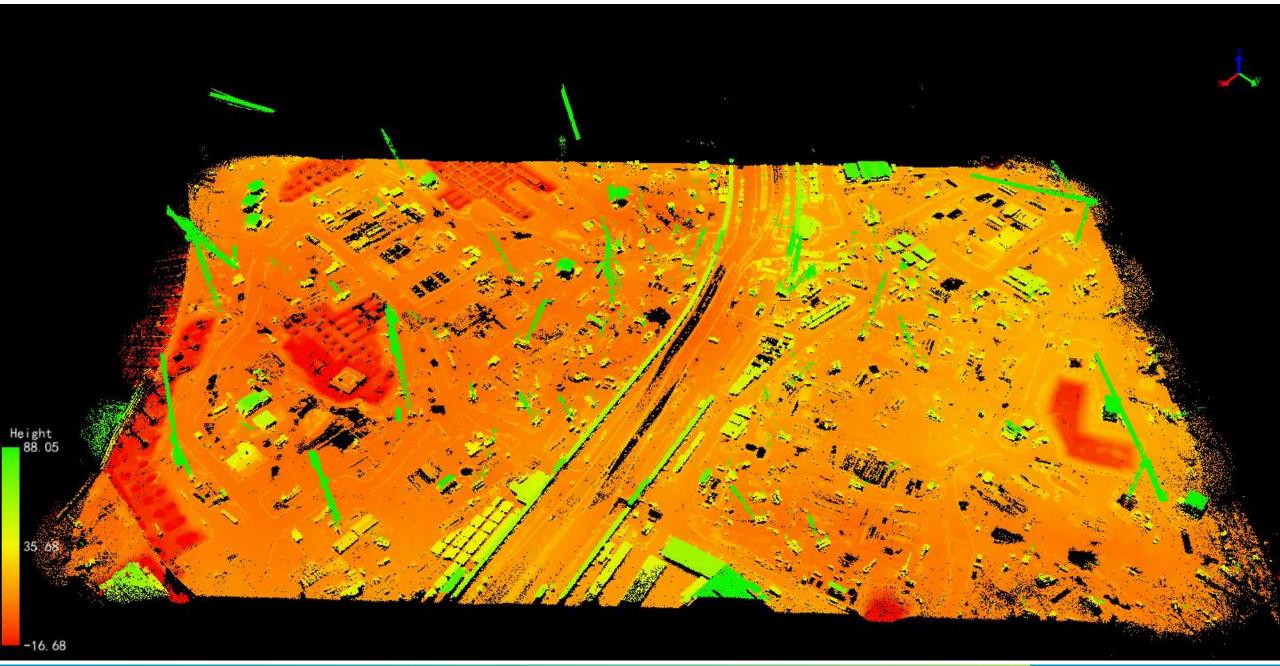




Colorized Point Cloud

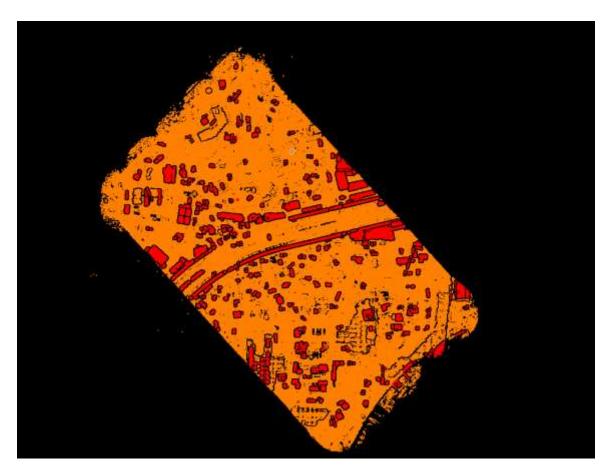


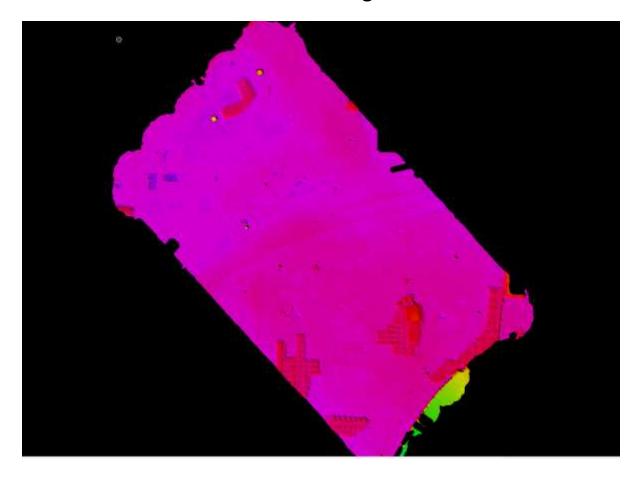
Point Cloud Colored by Elevation



True terrain model by Point Cloud Classification

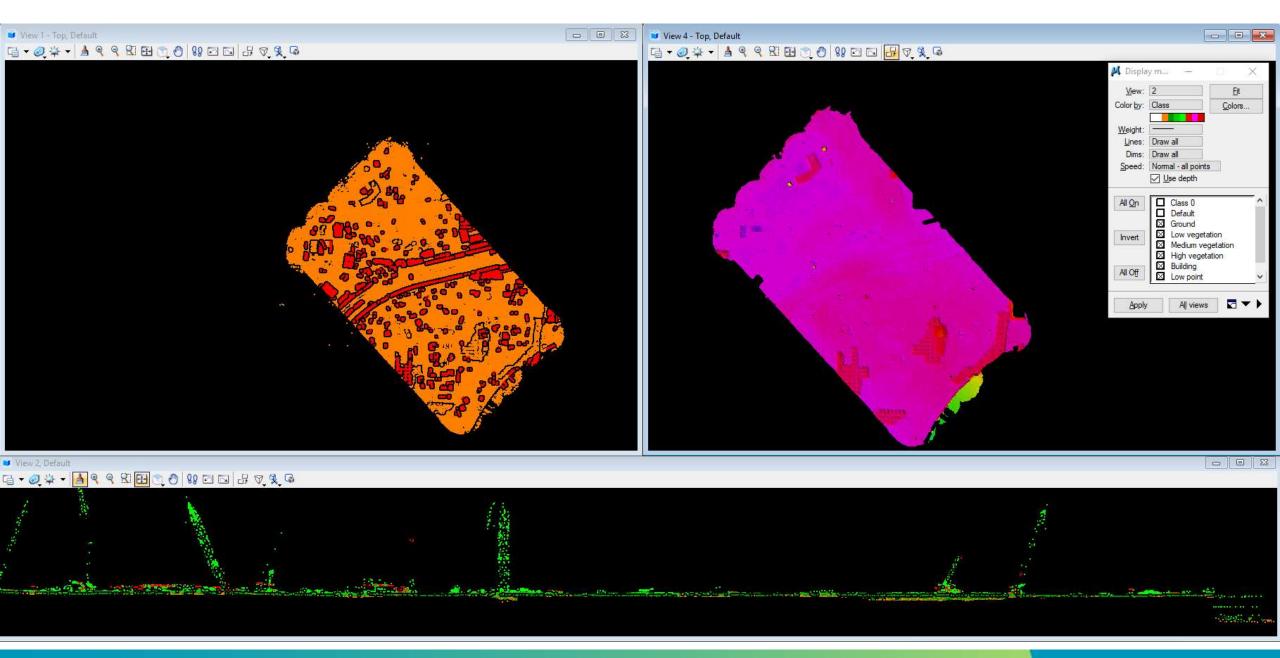
Use Terrasolid TerraSCAN + TerraModeler to build true DTM from editable TIN grid

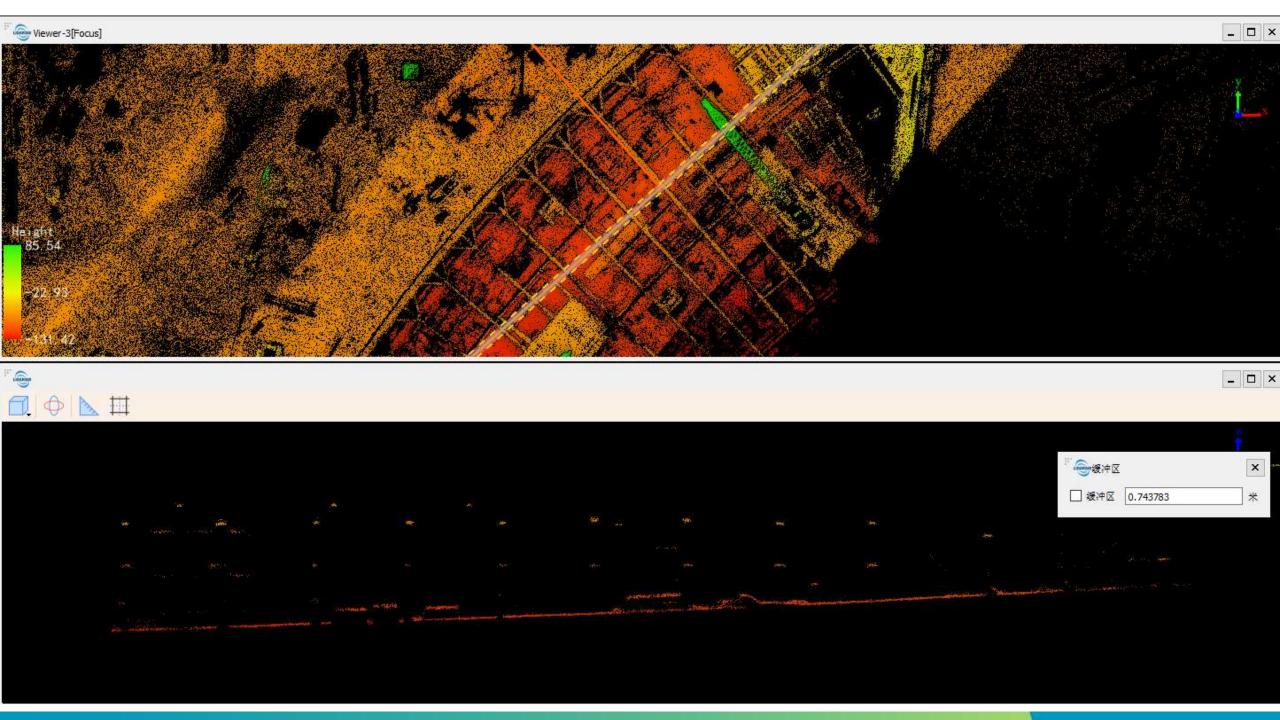


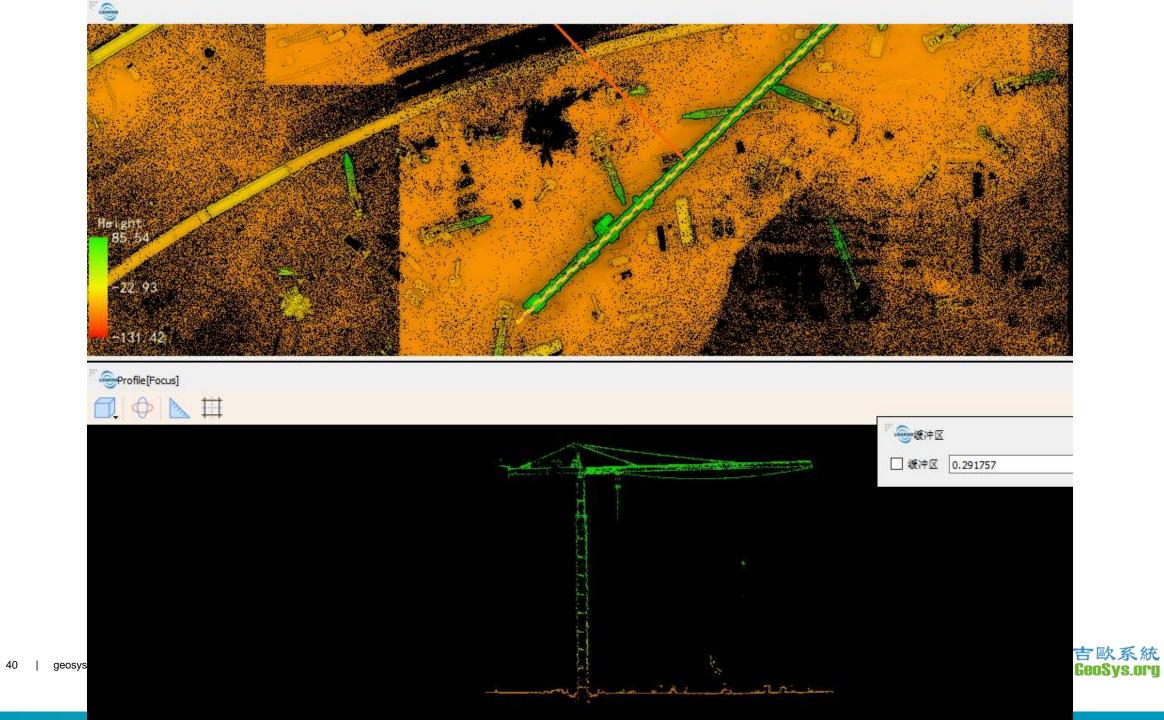


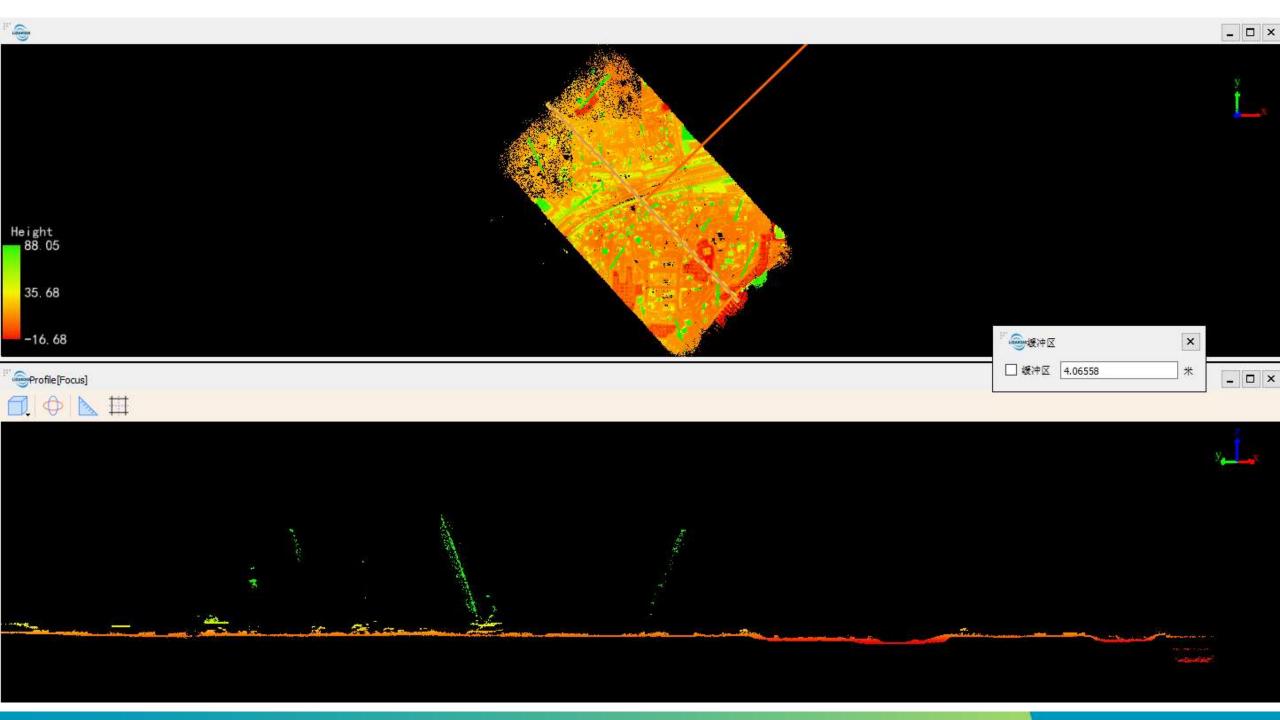


Editable Point Cloud with Sectional Tools



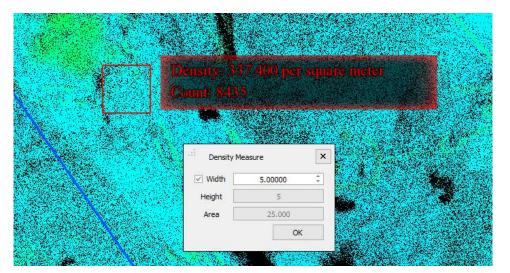


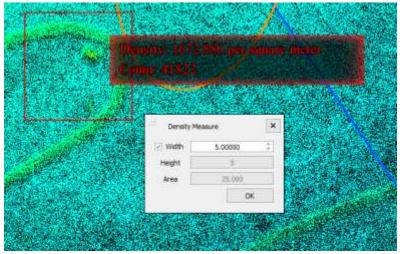


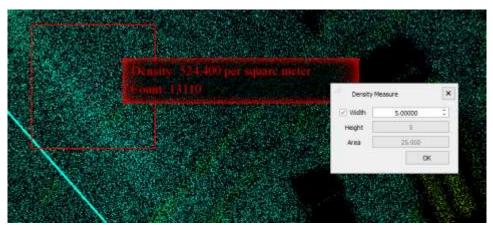


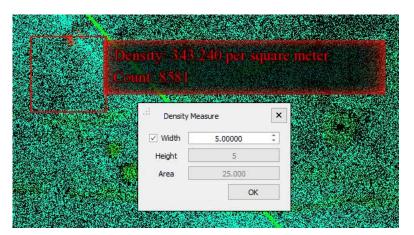


Point Cloud Density Measurement











UAV LiDAR flight at 海心公園

Flight height: 90m

• Flight speed: 3m/s

• Flight time: 21:30~22:50 PM

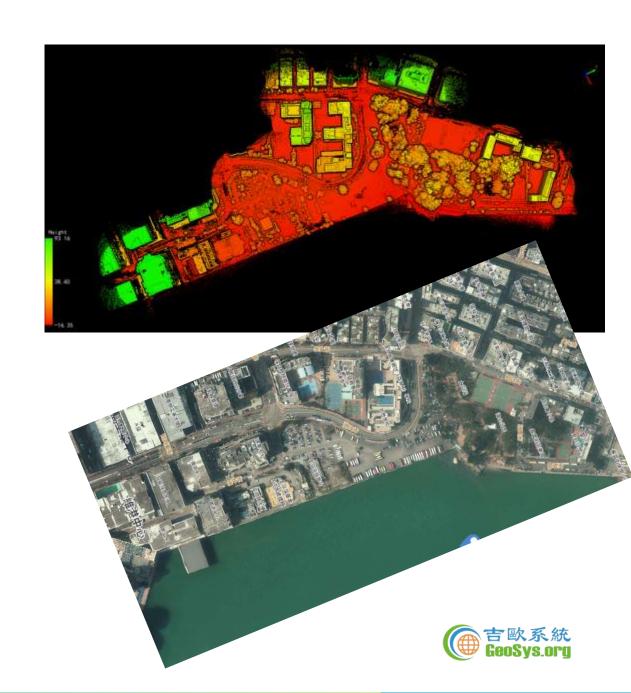
Point Cloud Density: 200~500 points/sqm

Point Cloud Thickness: 5~10 cm

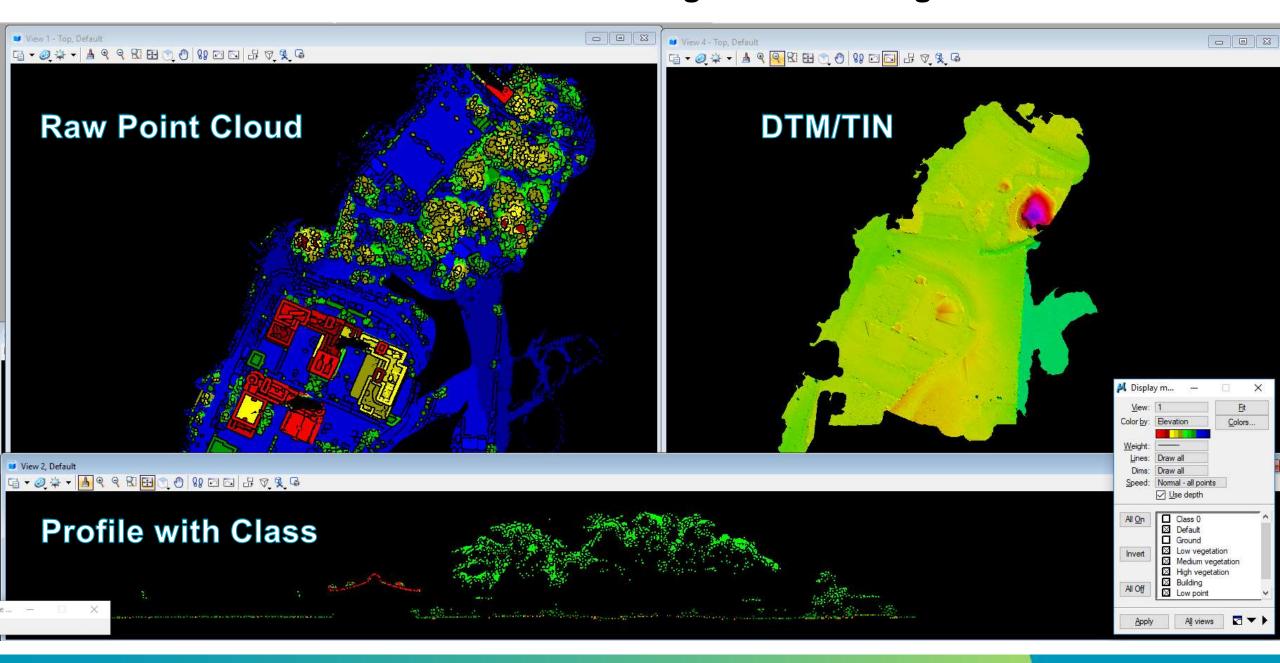
Point Cloud Accuracy: 5~10 cm

Number of Returns: 3

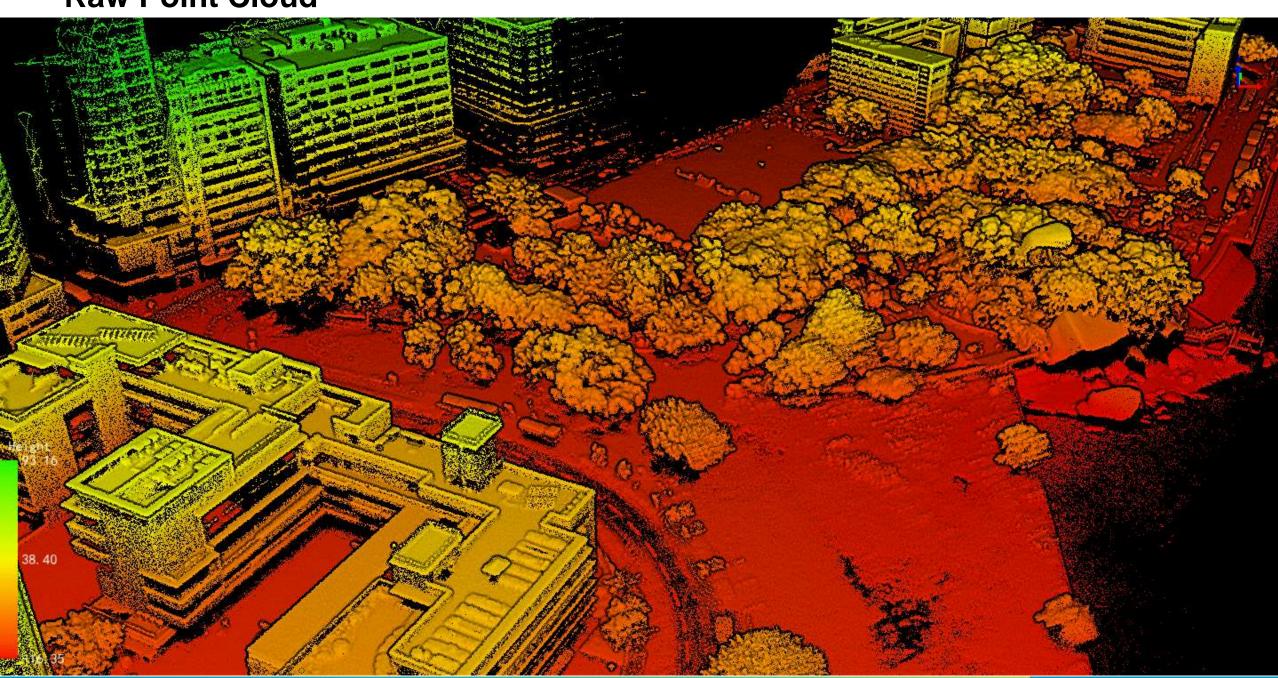
Flight mode : Manual + Route



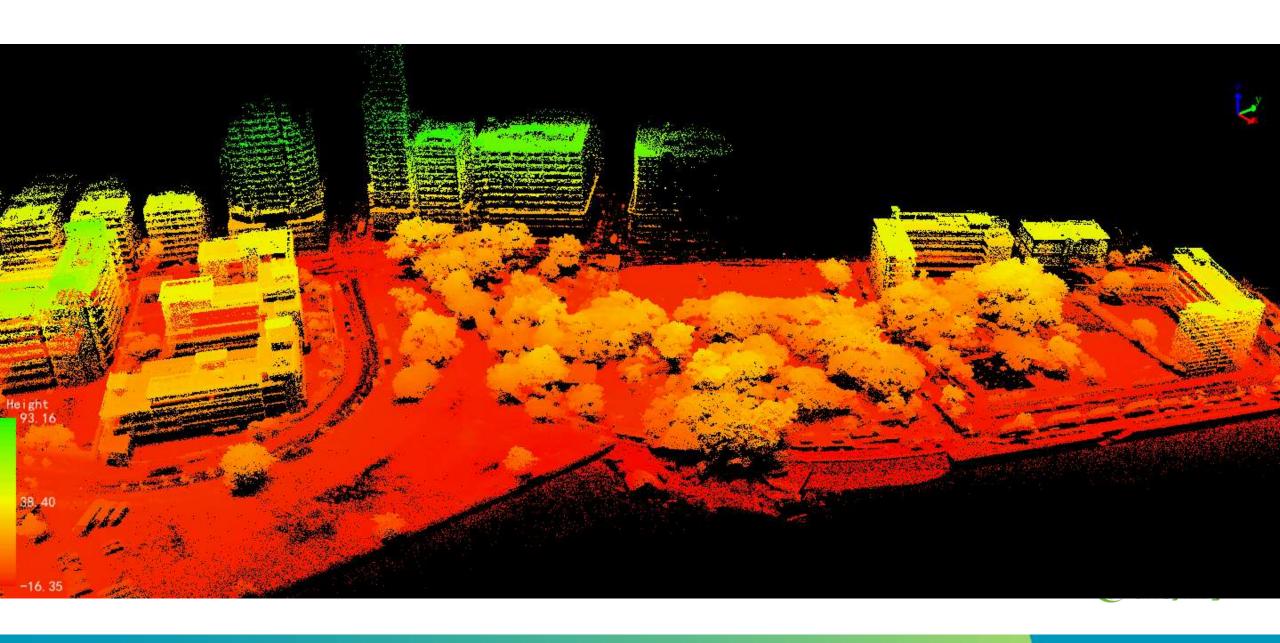
Point Classification Result – Ground / Vegation / Building

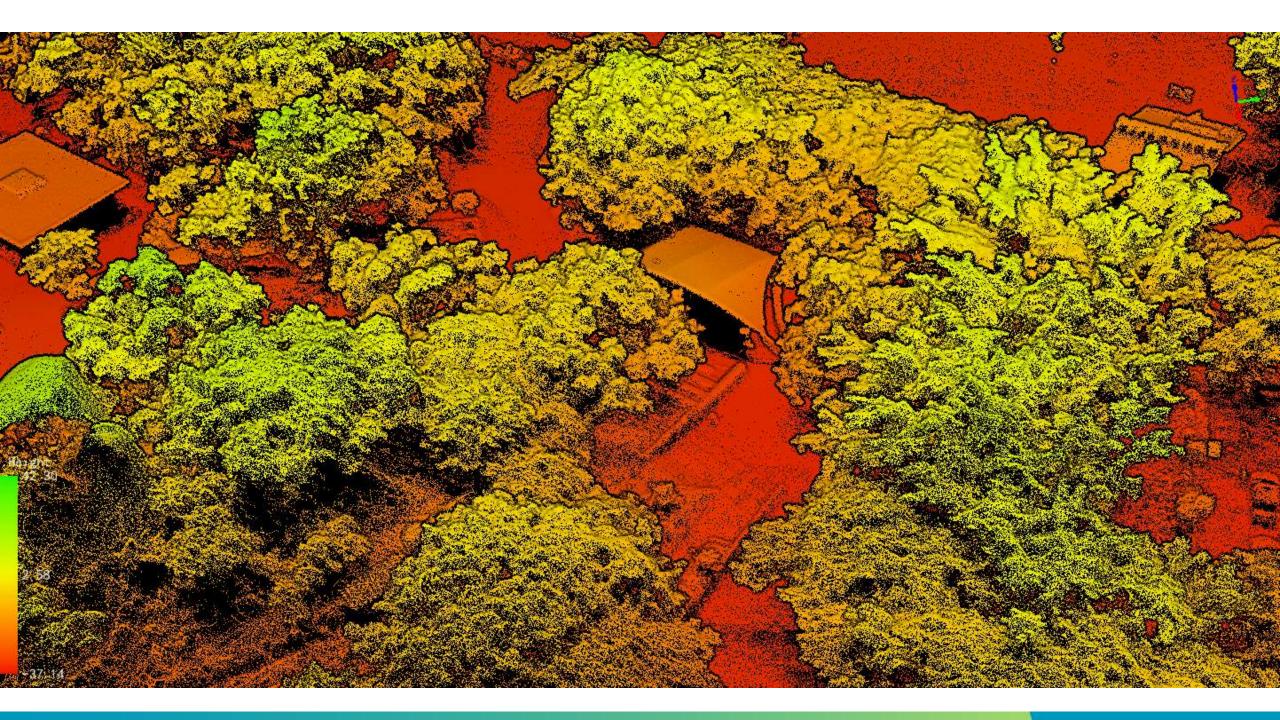


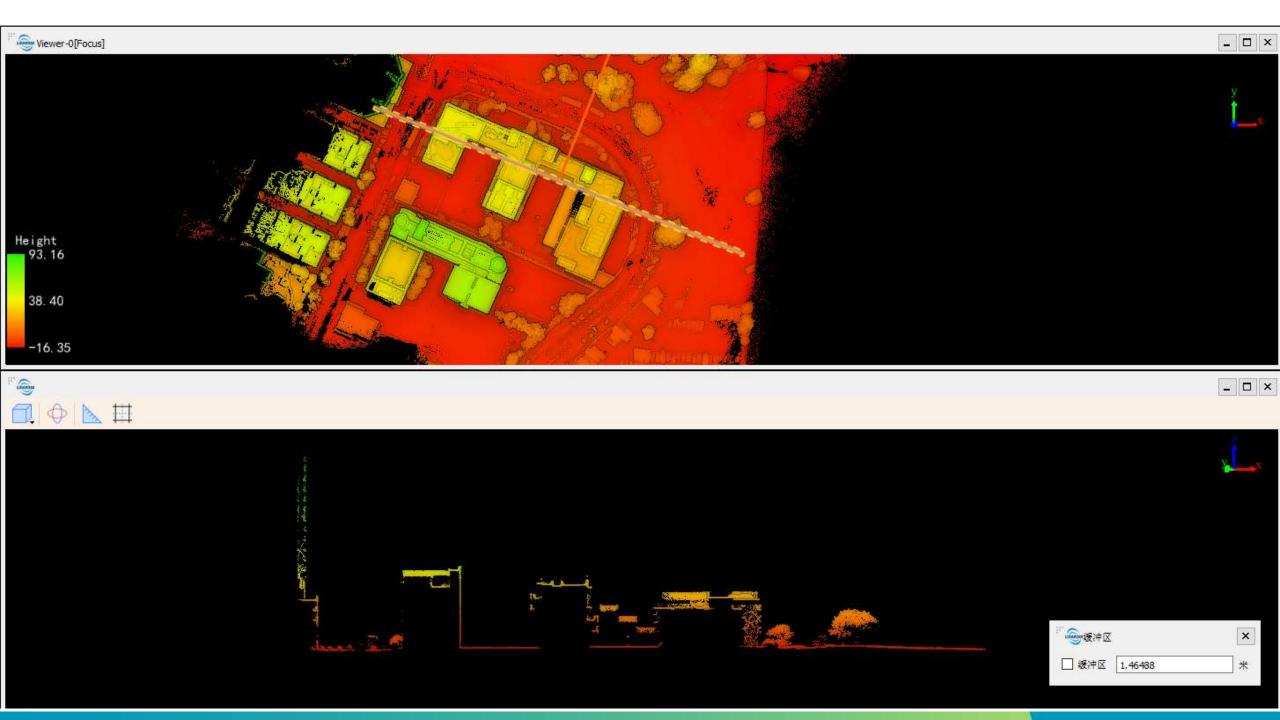
Raw Point Cloud

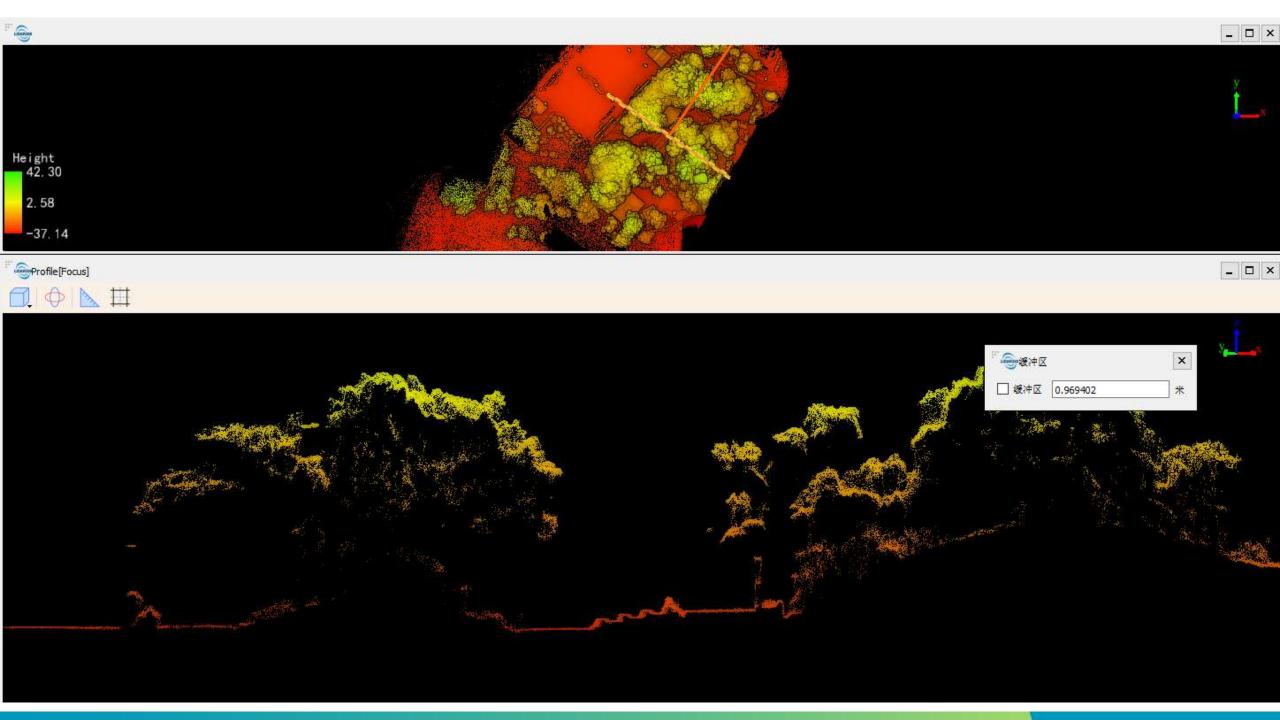


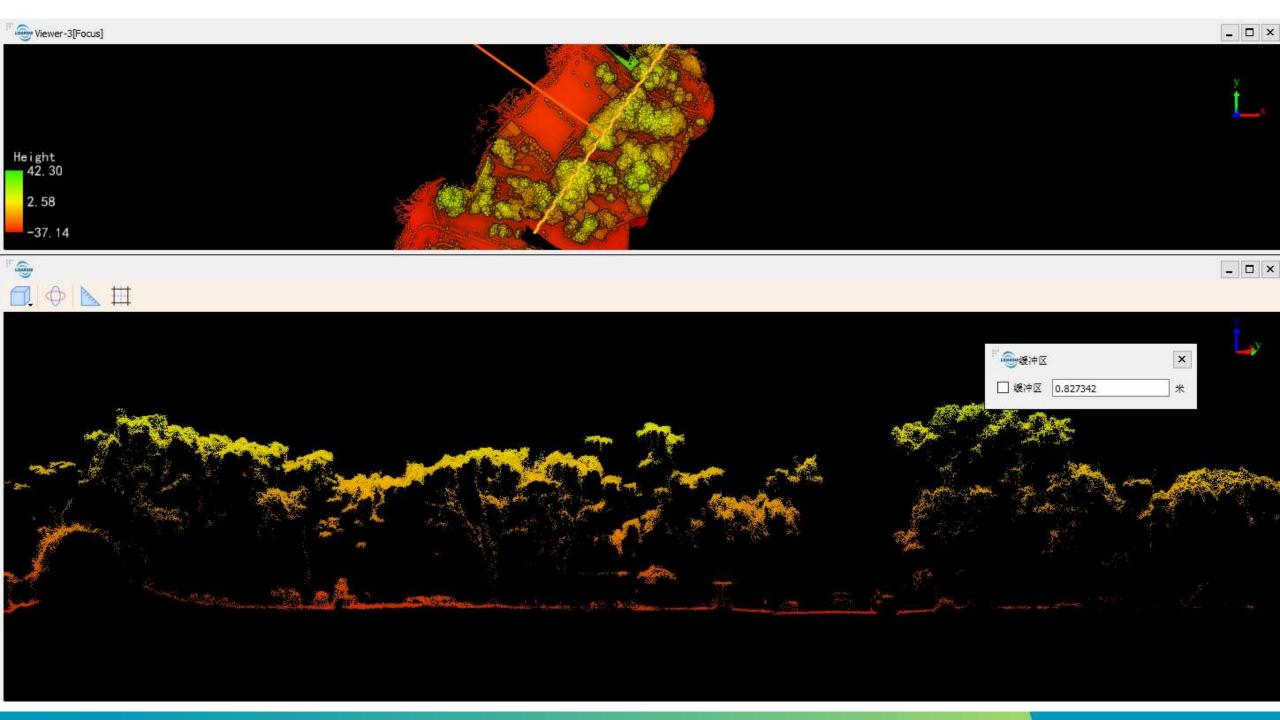
Raw Point Cloud











Point Cloud Thickness





Laser Scanner

Use the most advanced and accurate Laser Scanning device on the market with the professional team



We use the most accurate and suitable scanner system of 3D digital survey

Integrated Mobile Laser Scanning / Stop & Go Scanning / Mobile Scanning

Stationary Scanner-RIEGL VZ400i

• The RIEGL VZ-400i is a cutting-edge 3D Laser Scanning System which combines a future-oriented, innovative new processing architecture and internet connectivity with RIEGL's latest waveform processing LiDAR technology.



Backpack Scanner -PX8000

 PX8000 is the one of the most advanced Mobile Mapping System, and issused in 2019.
 Based on the SLAM-RTK technology, it integrates GNSS receiver to achieve the real-time positioning + SLAM for no-stop indoor and outdoor 3D digital surveying with Point Cloud and 720 Panorama, which made the data more accurate and efficient.



RIEGL VZ-400i specifications

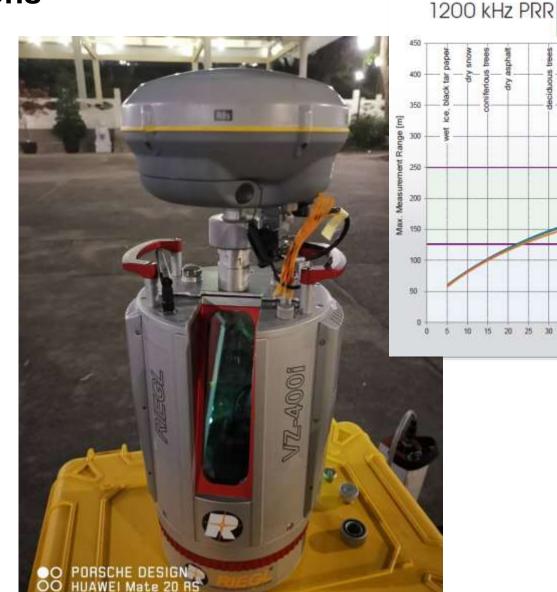
- Max. range **800m**
- Effect. meas. rate up to 500,000/sec.
- Cloud Connectivity via WiFi and 4G LTE
- MEMS IMU for pose estimation

Pose sensors

• Tilt sensors, compass gyros, barometric sensor

Post-processor

- Data post-processing
- e.g. data conversion, registration





standard clear atmosphere: visibility 23 km

MTA 2

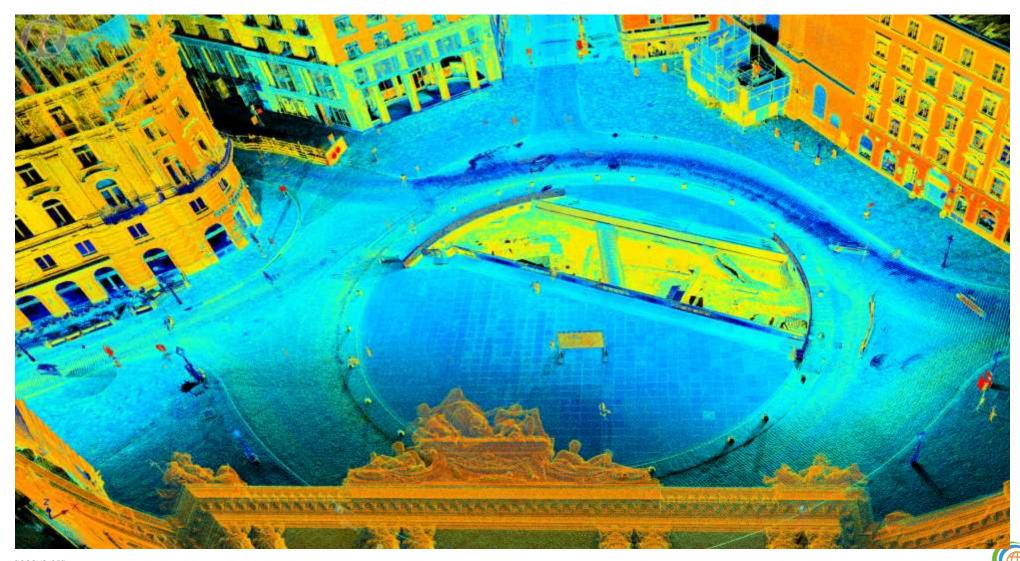
MTA 1

General deliverables for the terrestrial laser scanning

- Capture LiDAR Point Cloud data by terrestrial Laser Scanner
 - Laser Scanner System Range Measure Accuracy within +/- 5 mm in 800 meters range
 - POS system integrates RTK GNSS and High Accuracy IMU system
 - Capture 720 degree panoramic images by 6 angle cameras with at least 20MP each
 - Stitch 6 images from different angle into one panoramic image in at least 8192x4096 pixels
 - POS data of each panoramic image in txt/csv format with X, Y, Z, Direction
- Deliver 3D Point Cloud in LAS (and PLY/E57/XYZ (optional))
- Stitched 720 degree panoramic images with XYZ coordinate and direction.
- All geospatial data deliver in Hong Kong 1980 grid coordinate system and HKPD



Sample data of RIEGL VZ400i



Sample data of RIEGL VZ400i





PX8000 Mobile Backpack 360 Laser Scanner specifications

| Range | 0-100m | |
|--------------------|---|--|
| Total Weight | 10kg | |
| Acquisition Rate | 2*300,000 pts/sec | |
| Output | Colored point cloud/Panorama photos/POS | |
| Connectivity | WIFI | |
| Supported RTK Mode | Qianxun SI/CORS/Base Station | |
| | VRS/SatRef/NTRIP | |
| Coordinate System | WGS84 / CGCS2000/HK1980/ | |
| | UTM/Local Coordinate | |
| FOV | 360° | |
| Camera Type | FLIR® Ladybug 5+ | |
| Pixel | 6*5MP | |
| Image Resolution | 8192*4096 | |
| Relative Accuracy | <3cm | |
| Absolute Accuracy | 3-5cm | |



- ➤ SONY pregius CMOS
- ▶ 60 FPS high images acquisition rate
- ▶ 100% of full sphere
- ► Multiple Operation modes
- ➤ 30 km/h by vehicle operation
- No need for initialization RTK-SLAM mode



General deliverables for the terrestrial mobile laser scanning

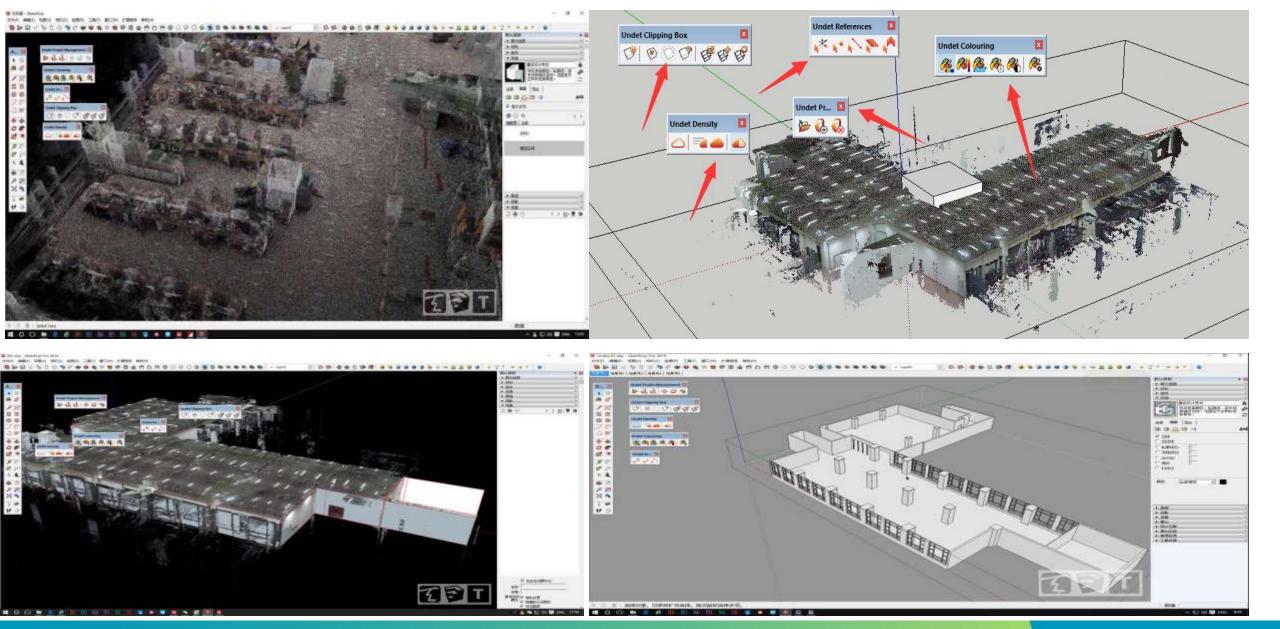
- Capture LiDAR Point Cloud data by terrestrial Laser Scanner
 - Laser Scanner System Range Measure Accuracy within +/- 10 cm
 - POS system integrates RTK GNSS and High Accuracy IMU system
 - Capture 720 degree panoramic images by 6 angle cameras with at least 5MP each
 - Stitch 6 images from different angle into one panoramic image in at least 8192x4096 pixels
 - POS data of each panoramic image in txt/csv format with X, Y, Z, Direction
- Deliver 3D Point Cloud in LAS (and PLY/E57/XYZ (optional))
- Stitched 720 degree panoramic images with XYZ coordinate and direction.
- All geospatial data deliver in Hong Kong 1980 grid coordinate system and HKPD



Mobile Laser Operation in different environment, Hiking / Bicycle / Urban

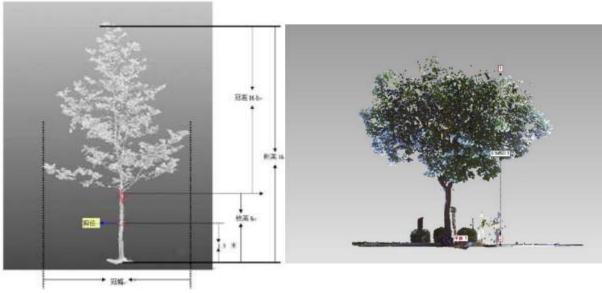


Scan to BIM using Mobile Laser Scan

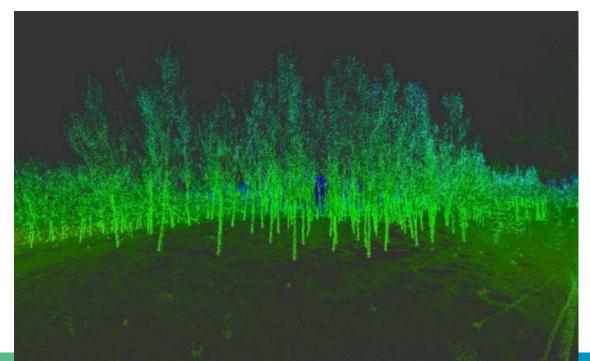


Forestry and Tree Management by VR3D MMS

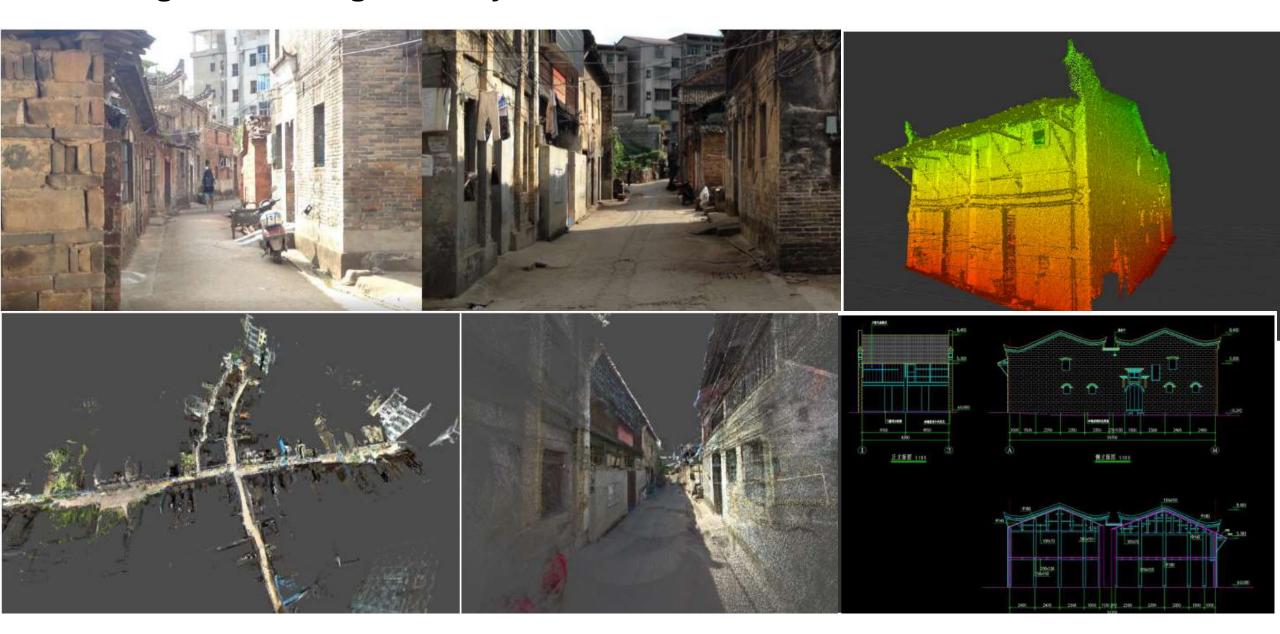






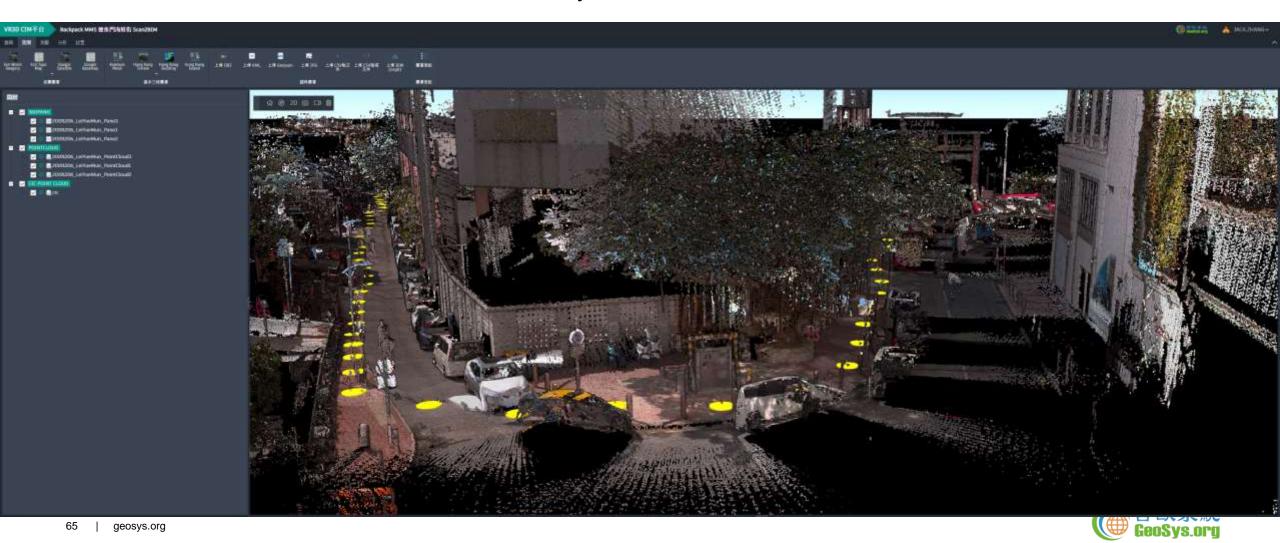


Heritage site management by VR3D MMS



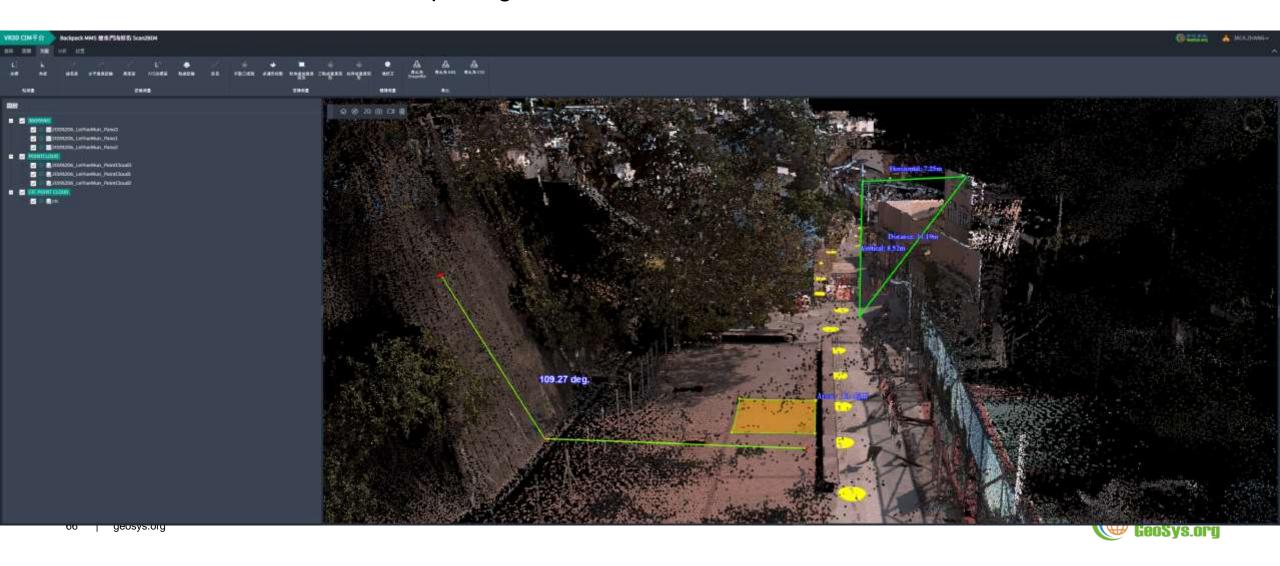
Sample Result of the Backpack Mobile Laser Scanning

Point Cloud in 3D with true color and overlay with GIS / Civil 3D BIM data



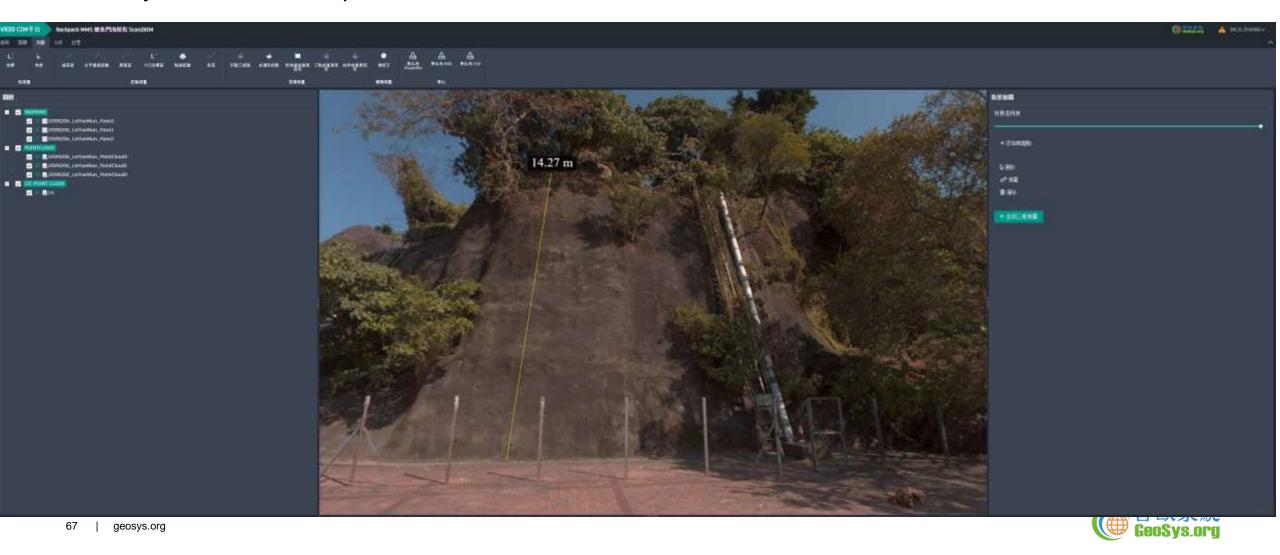
Sample Result of the Backpack Mobile Laser Scanning

Take Measurement such as slope angle, distance, area, volume and save as ESRI SHAPE FILE



Sample Result of the Backpack Mobile Laser Scanning

Overlay 360 streetview panorama with BIM/GIS data



Geosys VR3D Mixed Reality Application System

The first single Cloud Platform with AI + GIS + BIM+ UAV management functions









Geosys VR3D Apollo Data Management System

Imagery

(LAS)

Provides comprehensive Data Management and Delivery.

Desktop Use Geographic Information **Deliver Data** and Information Web Services

Mobile

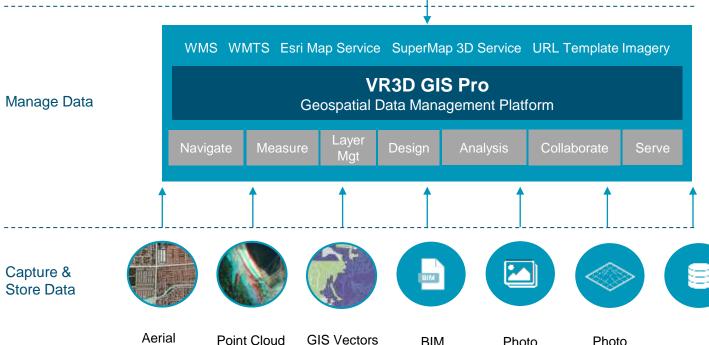
 Design & Analytics · Securely disseminate massive volumes of

Data Management

geospatial and business data

Enables an organization to:

Analyze



BIM

Photo

Photo

Mesh

Product Tiers

CIMS

PMS

DMS

DPMS





Geosys VR3D GIS Platform

A CITF Pre-Approved Technology (PA18-002)

info@geosys.org





Geosys Free Desktop Viewer for UAV Geospatial Data

Site Photos Viewer (DOM, Photo, DSM)

- Import folders of images with geotag locations in Exit file
- Automatic extract locations and display images in 3D map with trajectories.
- Click and show thumbnails of each image
- Download Trajectory and Image as Kml



Mesh Model Viewer (for Reality Mesh Models)

- Support import Reality Mesh Models in Cesium 3D Tiles format
- Display mesh models in 3D
- Support measurement by point, path, distance, volume, terrain profile, etc.
- Can export measurement in Kml format



Point Cloud Viewer (For LAS format)

- Support import Laser Scan / Photogrammetry point cloud into 3D Viewer
- Support view point cloud in Color RGB / Elevation / Intensity
- Support Cut sections of Point Cloud
- Support measurement in 3D





Geosys VR3D Mixed Reality Platform (On Cloud or On Premise)

Product Modules

Photogrammetry Data Management

- Manage 3D and 2D surveying data
- Support Pix4d / ContextCapture / Smart3d
- Support Laser Scanner
- Support ESRI / Supermap
- Create Workspace to share online
- User / Role management
- Steaming 3D/Raster data via internet with SSL and Smart Caching and Tiling



GIS + IOT Management

- Query Database From Gdb, PostGreSQL, MSSQL, Oracle
- Support WMS,WFS, ESRI Rest Service
- Support ESRI Rest Service, OGC WMTS, WMS, WFS
- Support publish kml, Fgdb, Shape file, dxf, dgn as Web Map Service.
- Support publish TIFF, IMG, ECW as Web Map Service
- Display data feed from IOT devices
- Data dashboard to show charts and plots



BIM+GIS Management

- Support Publish OSGB, IFC, RVT, 3D Tiles, Obj, 3DS as 3d web map service.
- Support load 4D information from Navisworks and bind to BIM for progress animation
- Sectional tools and query control to view every details of BIM models
- Integrated view and measurement functions for BIM+GIS+Reality Models
- Collaboration and issue tracking with Forms, tasks and follow-ups



Planning & Design

- Powerful 3D GIS Analysis Functions for data on the server
- Viewshed, Shadow, Skyview, Volume difference, Slope, Radiation, flood analysis
- Support smart drawings and design on the 3D map
- Support upload dwg/obj/skp/shp to the server and overlay with any data ready on the system.
- Flythrough as bookmark or download in Mp4





Get upto 70% Service fee fund by CITF

https://www.citf.cic.hk/?route=search-key

• Search Technologies : VR3D



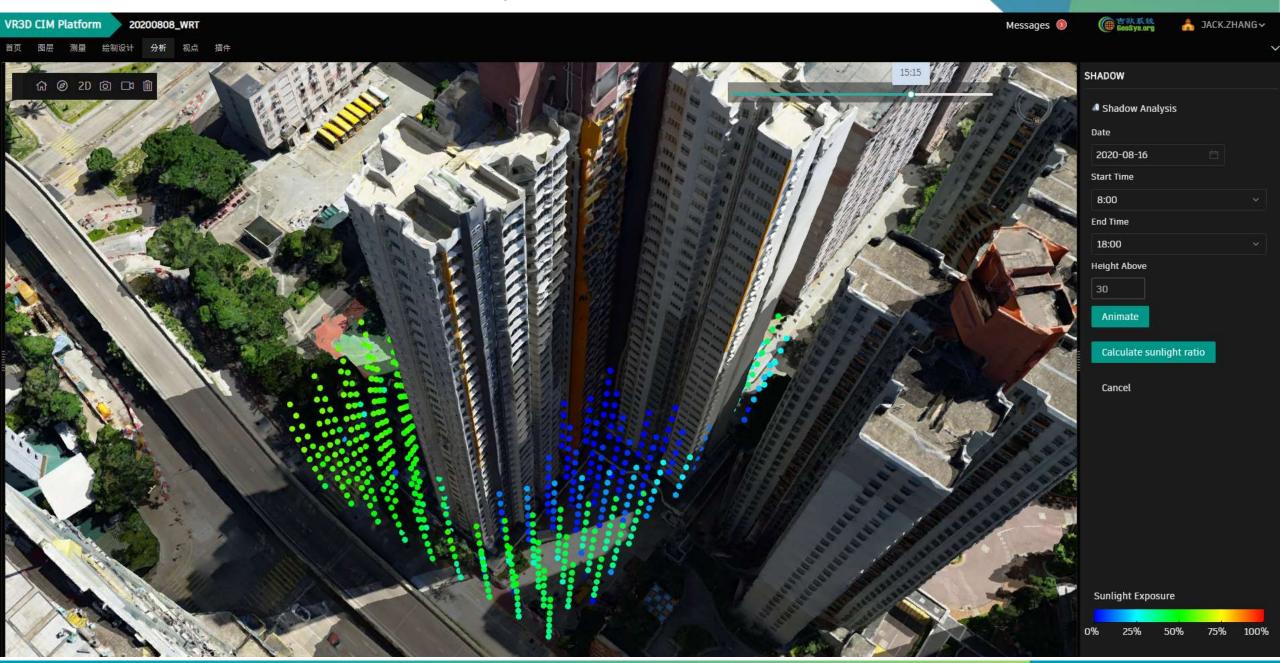
| Type of Technology | Product Type | Code | Distribution Channel | Product Descriptions | Reference Photo |
|-----------------------------|---|--------------|---|--|-----------------|
| Internet of Things (IoT) | 3D reality simulation / Data management (CDE- related) | PA18- 002 | Geosys Hong Kong Ltd Tel: 6198 5234 / +86 13088880388 | Geosys VR3D data management system support the visualisation of 3D GIS and BIM data in one integrated viewer for users with 2D and 3D measurement and analysis functions. Web based 3D Measurement tools such as distance, path, angle, height, Volume, Section are provided. Cloud and server-based system allows users to open the application without software installation and maintenance for different end-user's PCs (Note: This product is CDE-related platform which the vendor shall be inquired for details.) | |



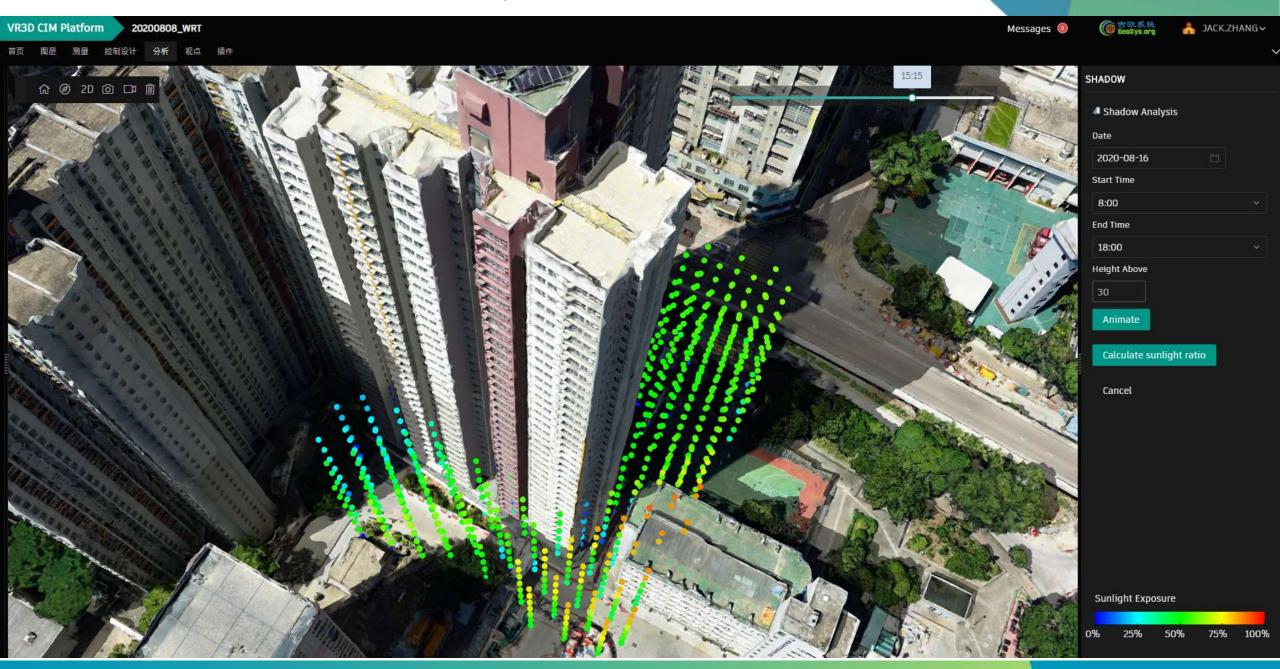
Shadow/Noise/Radiation analysis functions for EIA



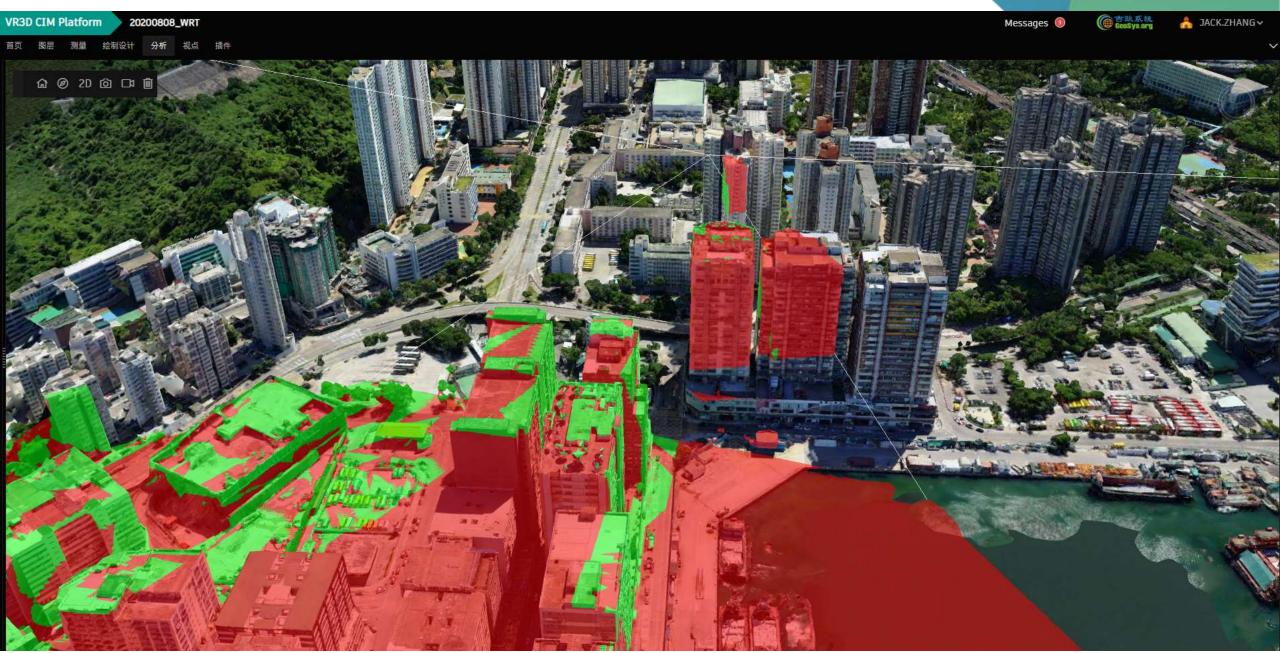
Shadow/Noise/Radiation analysis functions for EIA



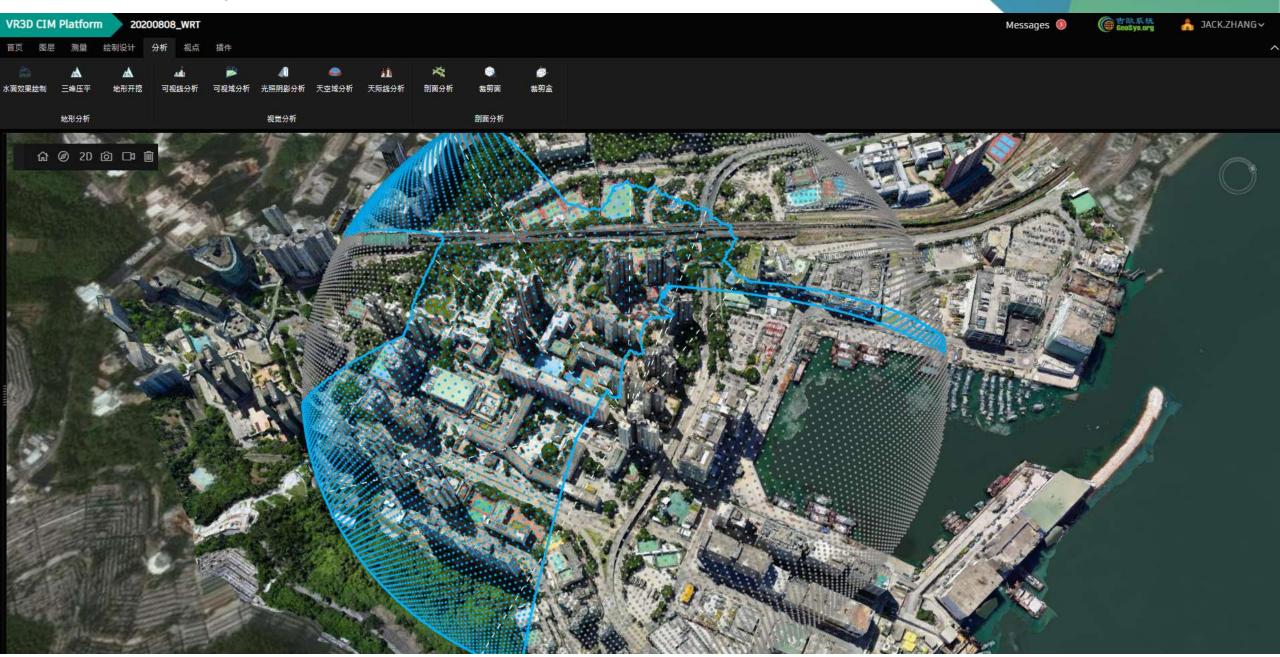
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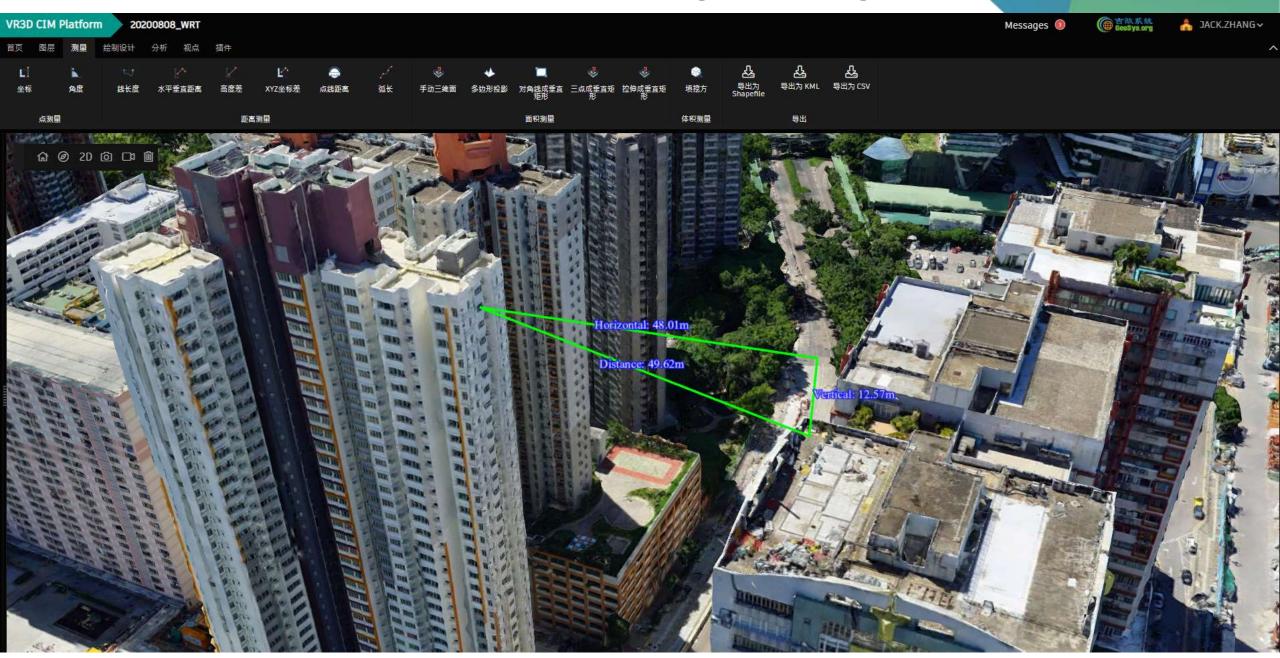
Visual analysis functions for Valuation



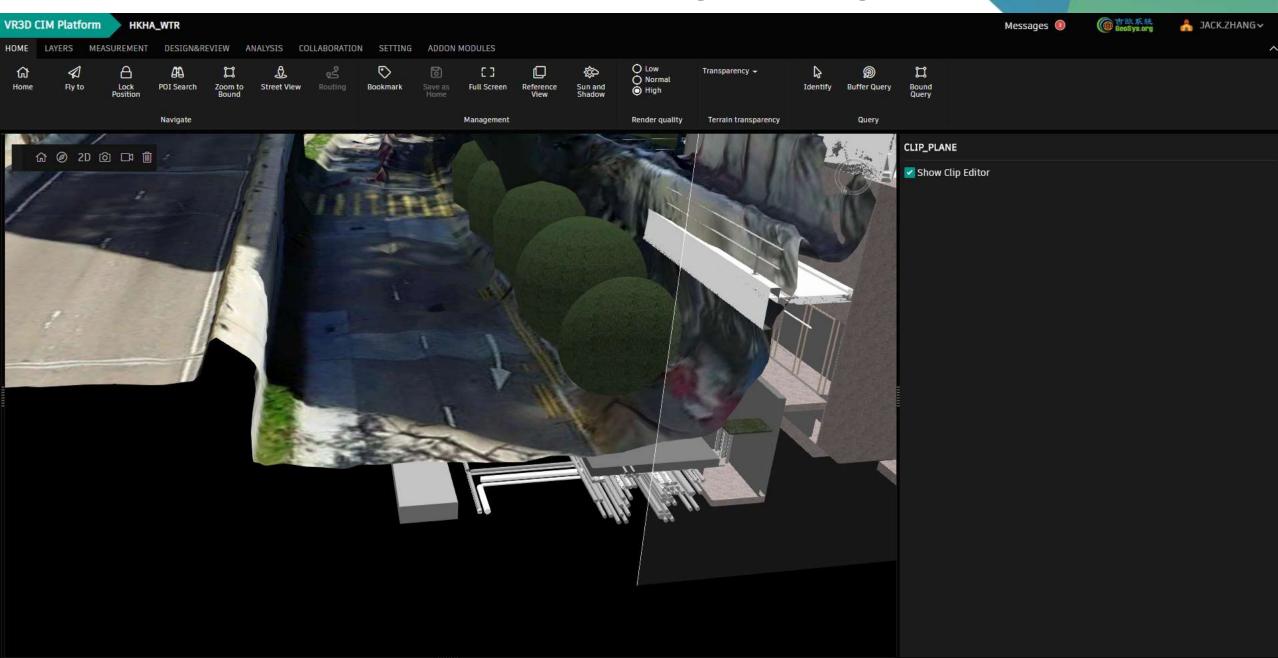
Visual analysis functions for EIA and Valuation



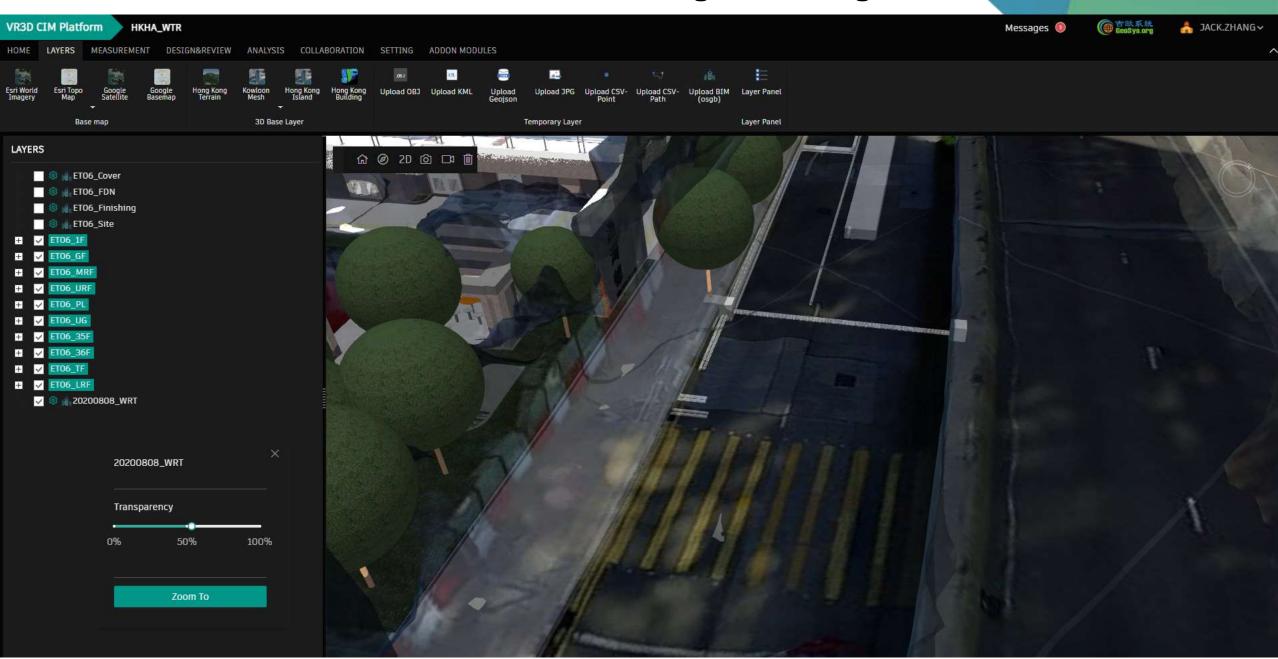
Measurement / Sectional tools for Planning and Design



Measurement / Sectional tools for Planning and Design



Measurement / Sectional tools for Planning and Design





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