

Certificate in Building Information Modelling (BIM) - Asset Management for EMSD Projects

9 Interfacing/ Integrating BIM-AM System with Other Systems 1

CONTENT

9.1	Laser scanning for BIM model construction to existing buildings
9.2	Verification of BIM Model by 360 spherical photos

9.1 Laser scanning for BIM model construction to existing buildings

Laser Scanning

- Laser scanning is a method of high-accuracy mapping or reality capture that uses laser beams to quickly capture complete detail of the entire building construction project - much like a camera taking a 360-degree photo, but with an accurate position for every pixel.
- Point Cloud - The detailed 3D representation of the building project.
- Originally applied in the construction and maintenance of industrial plant facilities, laser scanning has since been adopted for many other uses, including building construction and **building information modeling (BIM)**.

Building Construction Applications:

- Many modern building construction projects are renovations or redevelopments that lack current construction or maintenance documents on the existing facility.
- In these situations, the rich, complete data captured with a laser scanner can provide the required information on existing building conditions with the accuracy needed for construction planning.
- As construction progresses, laser scanning data can be used to compare the newly constructed work against the as-designed model or drawings for quality assurance.
- If laser scanning is used throughout the entire construction project, the new facility will have as-built documentation from all the major milestones in the project, creating a record of what is behind the walls, above the ceilings and under the floor slabs for owners to utilize throughout the lifecycle of the building.

Example 1 –

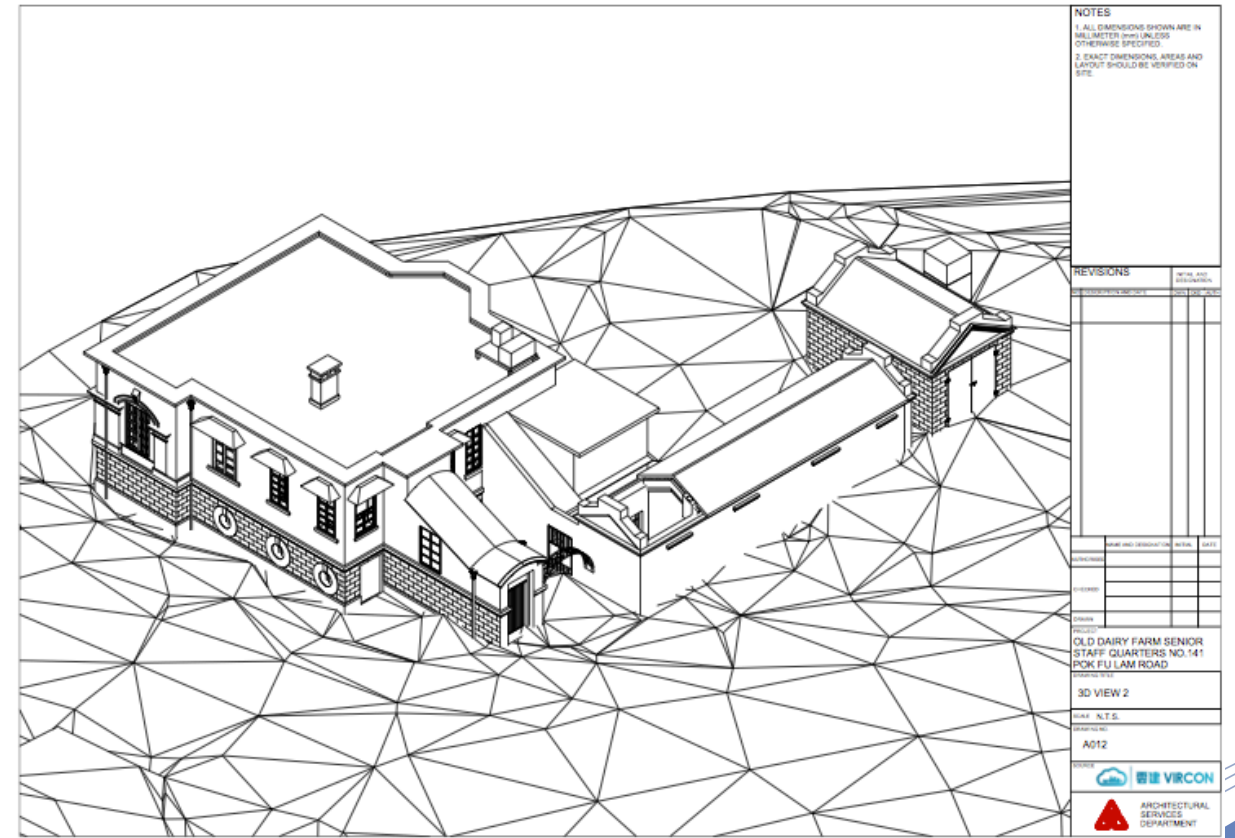
The Pokfulam Farm Project:

- Built in 1887, Grade I.
- The project presents the history of the Old Dairy Farm and introduces the culture of Pokfulam village and the surrounding area through exhibitions, guided tours and workshops



BIM Model:

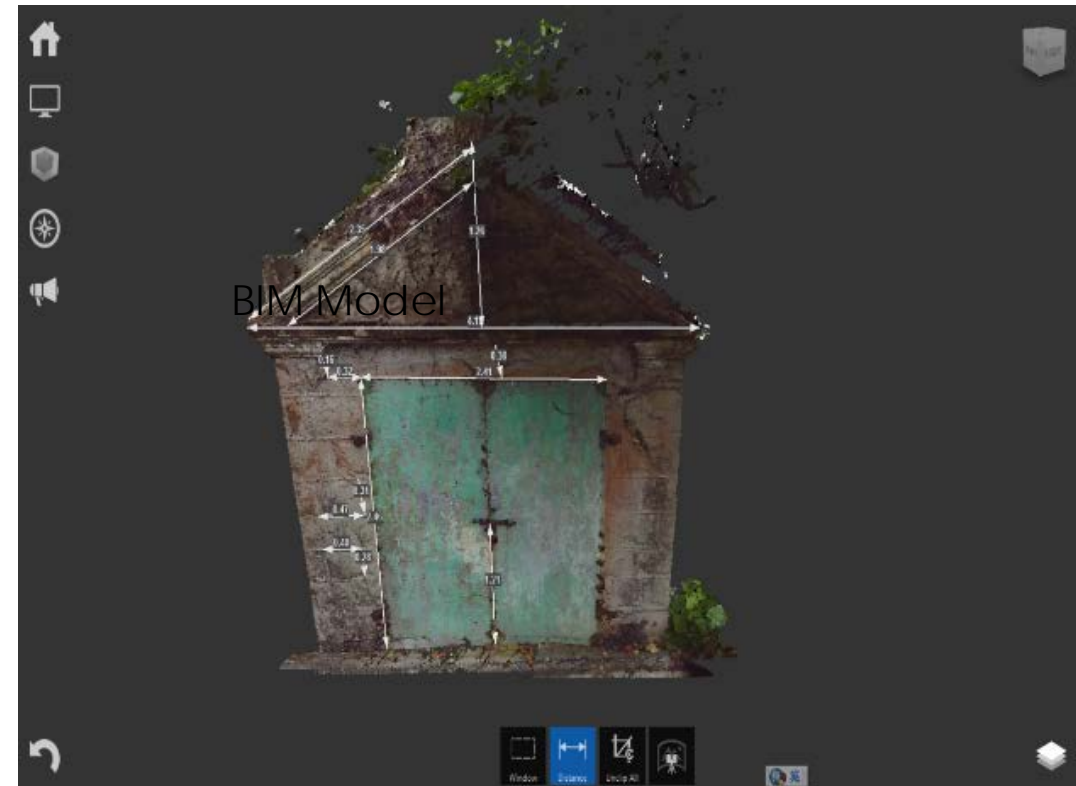
3D scanning data turned into BIM for heritage record and further design.



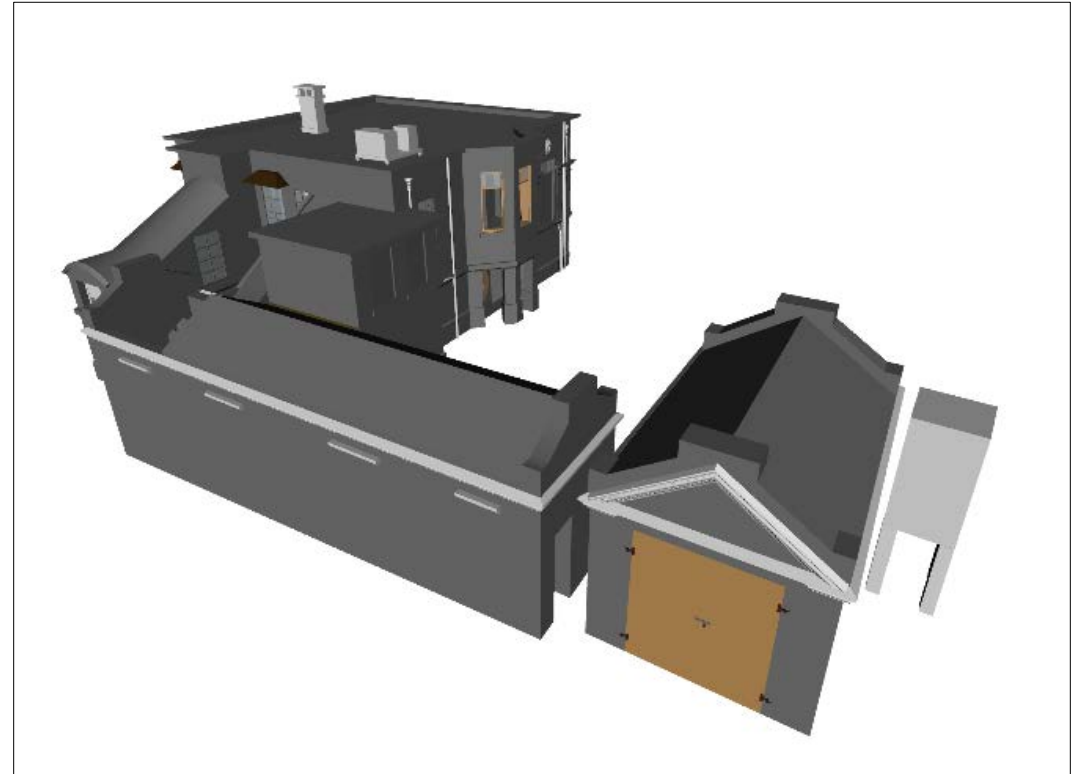
3D Scanning:



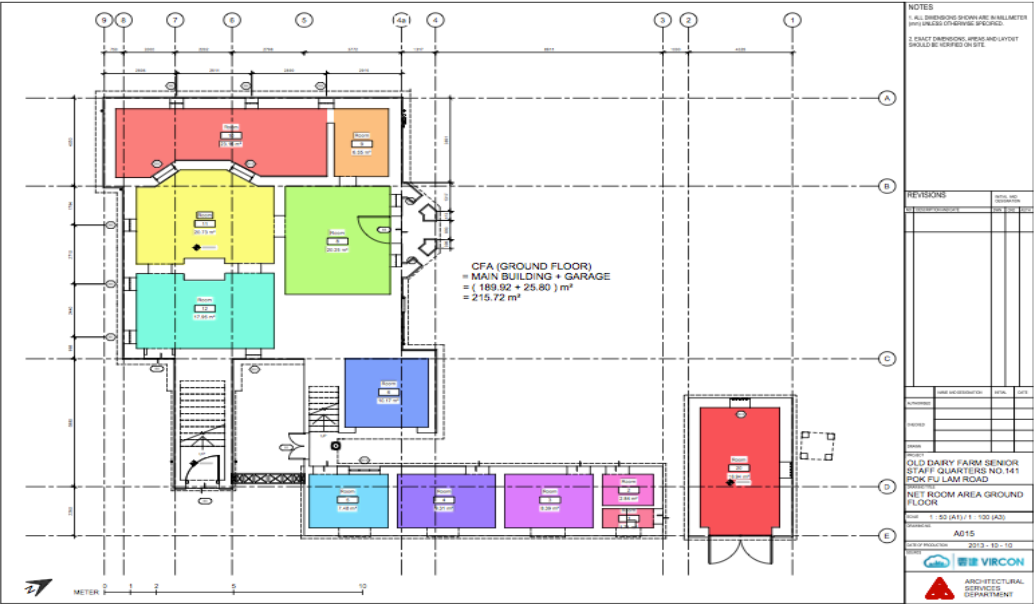
Point Cloud Data:



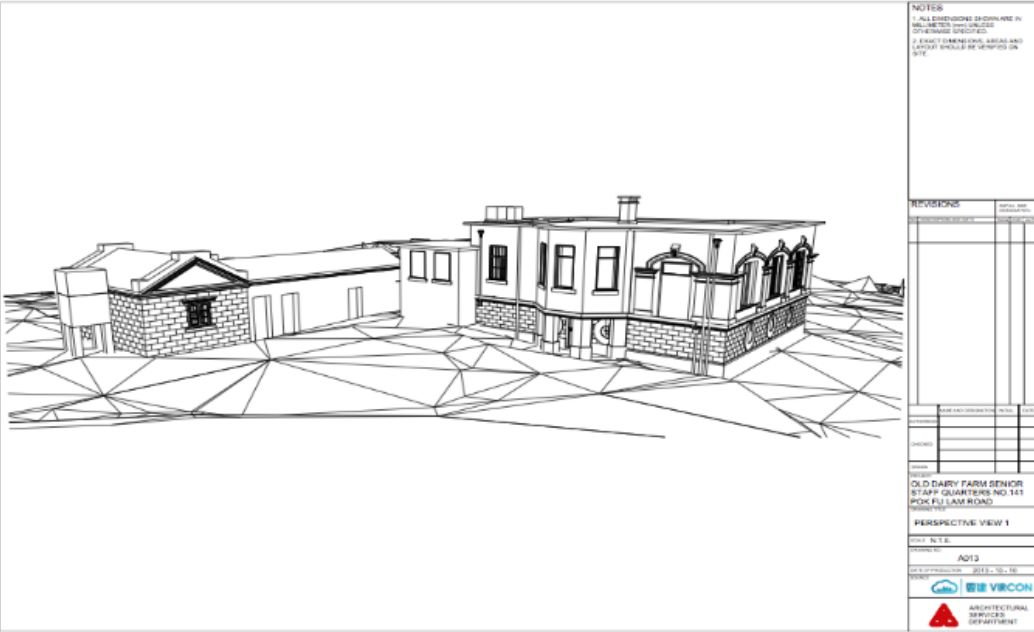
BIM Model:



Drawing Production and Quantity Take-off:



Room Schedule	
Name	Area
Room 01	10.37 m²
Room 02	6.65 m²
Room 03	24.67 m²
Room 04	24.61 m²
Room 05	4.53 m²
Room 06	21.89 m²
Room 07	24.25 m²
Room 08	23.20 m²
Room 09	10.55 m²
Room 10	7.48 m²
Room 11	25.21 m²
Room 12	24.35 m²
Room 13	21.31 m²
Room 14	9.55 m²
Room 15	4.30 m²
Room 16	9.73 m²
Room 17	7.48 m²
Room 18	1.84 m²



Example 2

- Ruins of St. Paul's, Macau:

- A long term monitoring project.
- A 6-months interval monitoring exercise

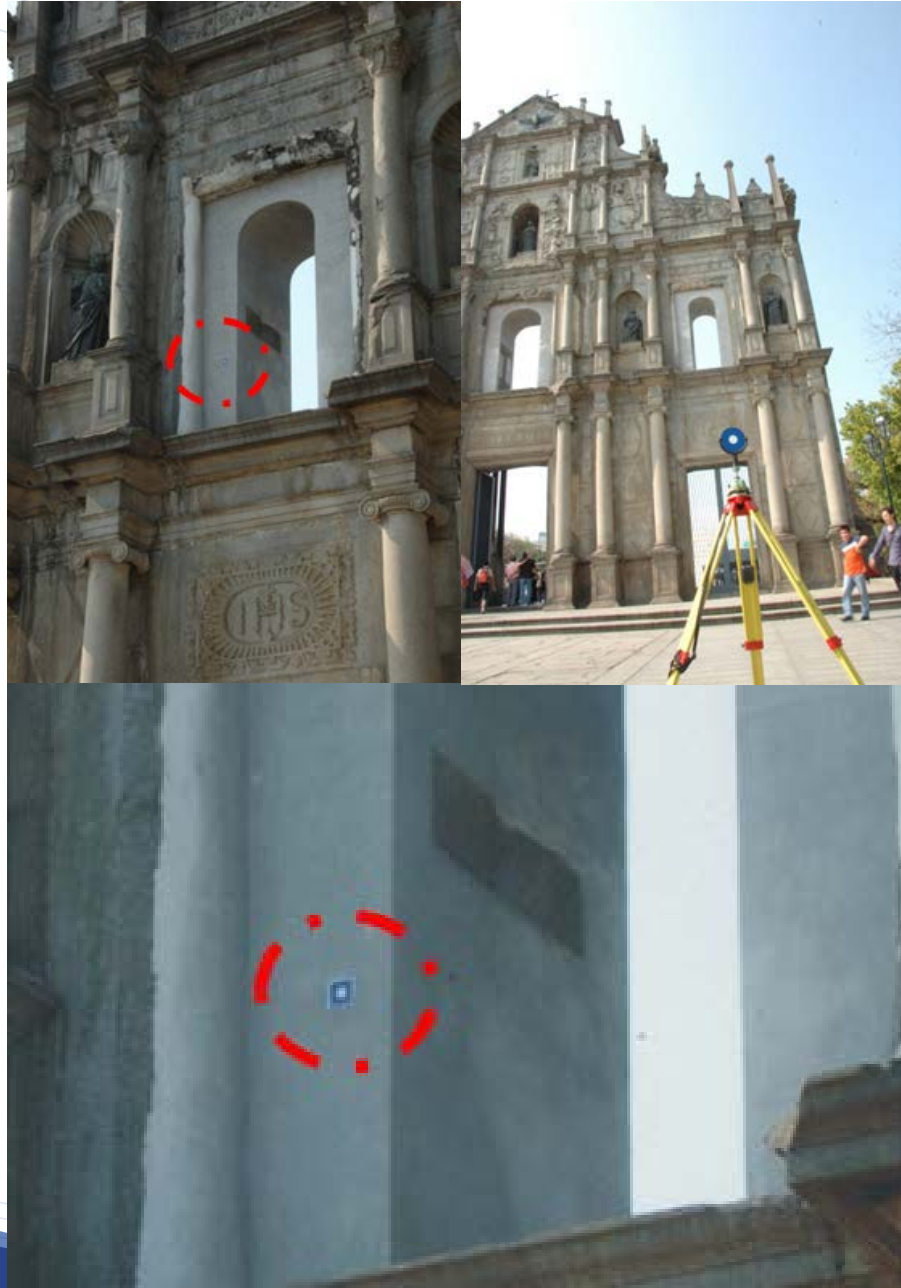
Setting Up:

- Two scanners are set-up at the selected positions and pointed to the direction of the required scans.



Targets Located:

- Targets are positioned within the region of Field of View (FOV) of scanner.
- Targets fixed on wall



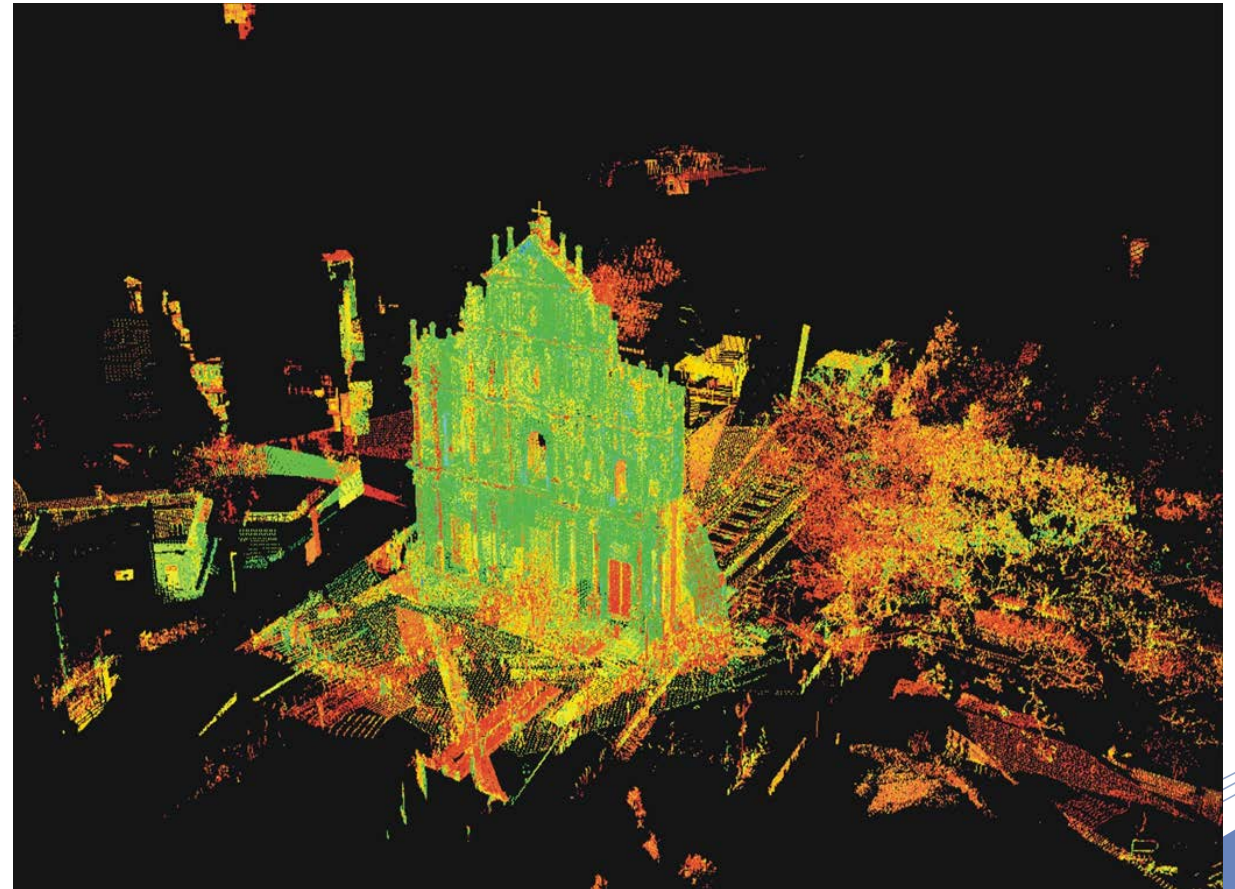
Field Scanning:

The field scanning is started after the setting up of scanner and targets located.

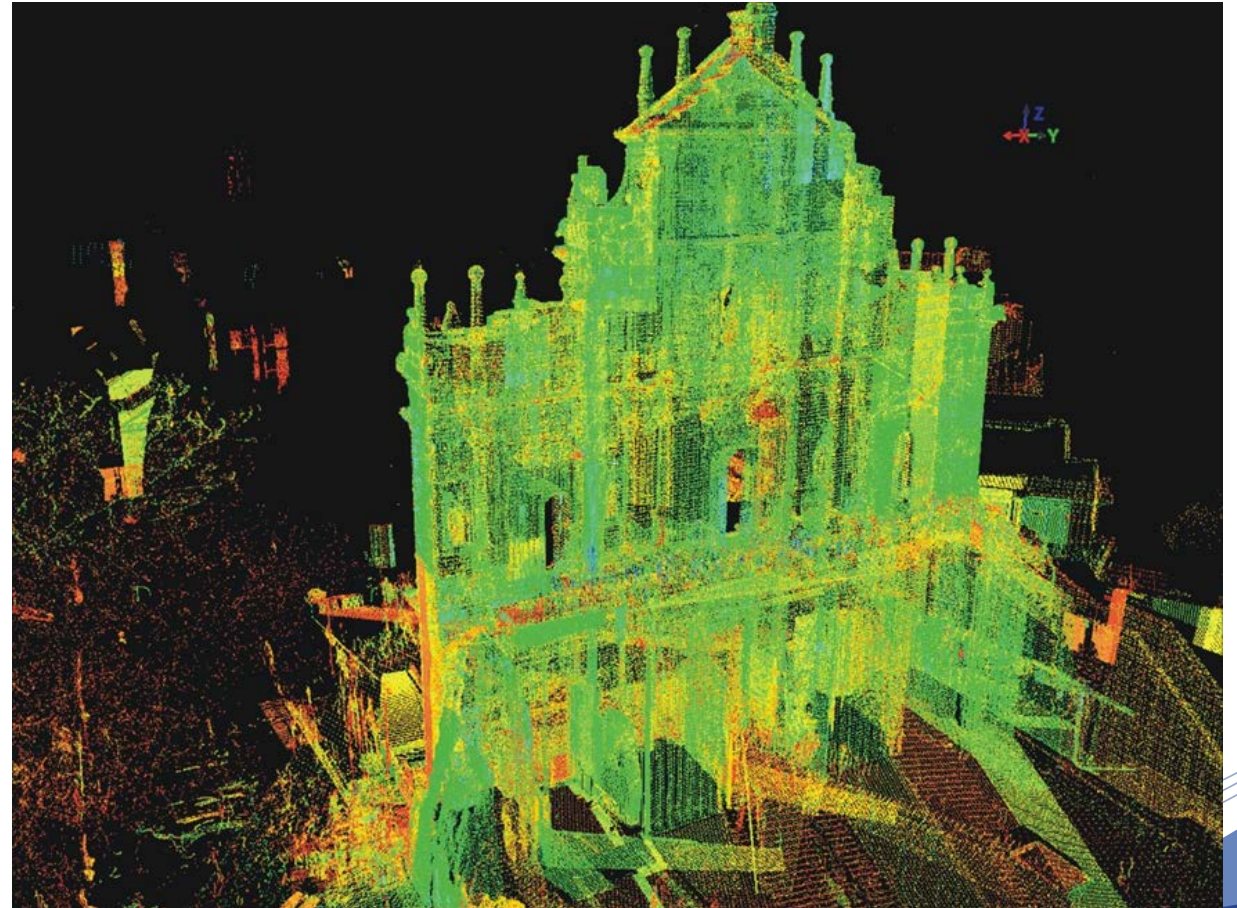


Scanning:

- Scanned point clouds (before noise removal)



- Scanned point clouds (before noise removal)



- Scanned point clouds in true colour (after noise removal)



- Scanned point clouds in true colour (after noise removal)

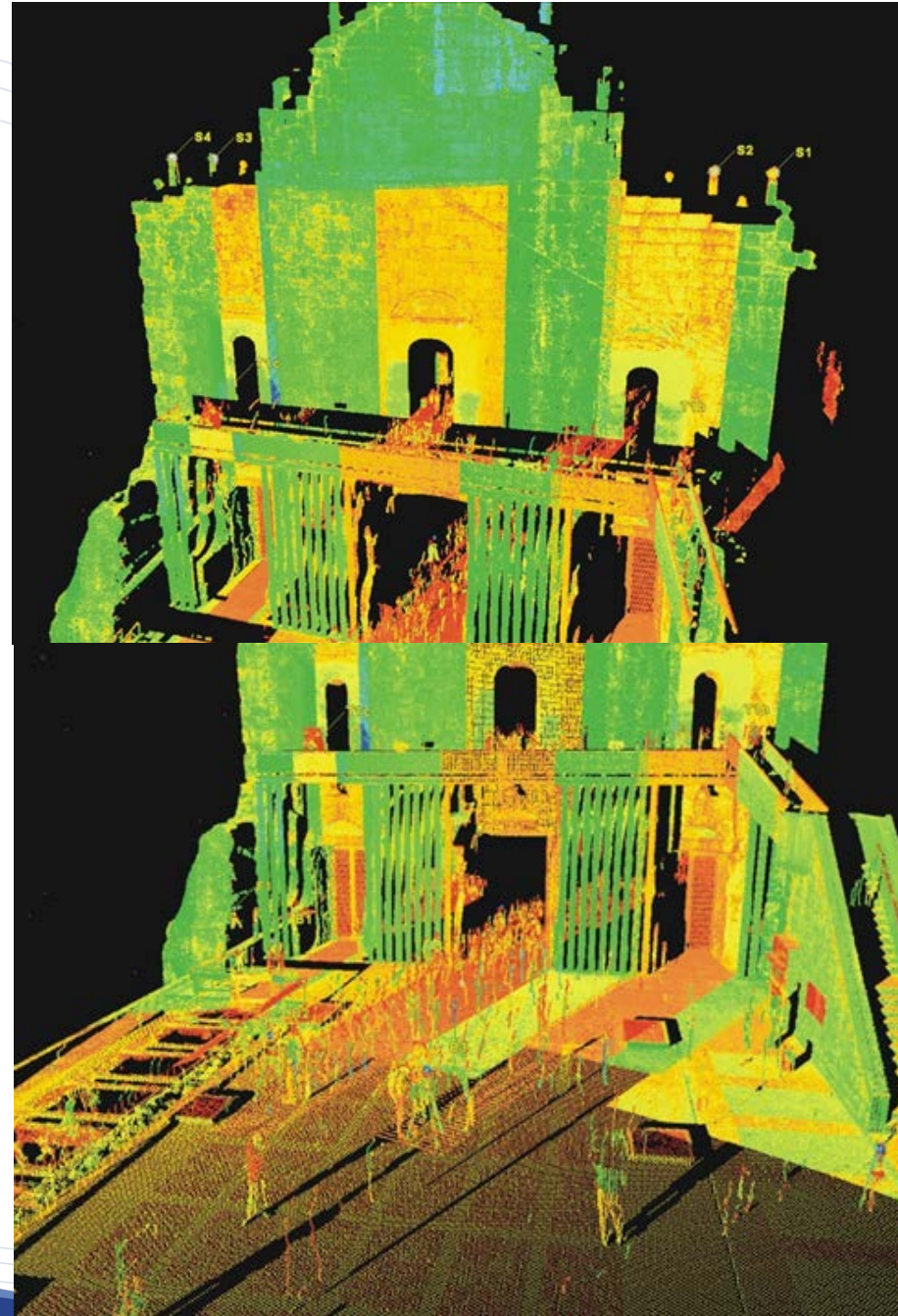








- Scanned point clouds in true colour (after noise removal)



Target Registration:

- Scanning of Targets located at known positions.
- Spherical objects were also used as target purposes.



Constraint ID	ScanWorld	ScanWorld	Type	Status	Weight	Error	Error Vector
 TargetID: B31	ScanWorld 4 (8Jul Outside2)	ScanWorld 3 (8Jul Outside2)	Coincident: Vertex-Vertex	On	1.0000	0.001 m	(0.000, 0.001, 0.000) m
 TargetID: B33	ScanWorld 4 (8Jul Outside2)	ScanWorld 3 (8Jul Outside2)	Coincident: Vertex-Vertex	On	1.0000	0.000 m	(0.000, 0.000, 0.000) m
 TargetID: B36	ScanWorld 4 (8Jul Outside2)	ScanWorld 5 (8Jul Outside2)	Coincident: Vertex-Vertex	On	1.0000	0.001 m	(0.000, 0.000, -0.001) m
 TargetID: B35	ScanWorld 4 (8Jul Outside2)	ScanWorld 5 (8Jul Outside2)	Coincident: Vertex-Vertex	On	1.0000	0.001 m	(-0.001, 0.000, 0.000) m
 TargetID: B30	ScanWorld 4 (8Jul Outside2)	ScanWorld 3 (8Jul Outside2)	Coincident: Vertex-Vertex	On	1.0000	0.001 m	(0.000, -0.001, 0.000) m
 Cloud/Mesh 1	ScanWorld 4 (8Jul Outside2)	ScanWorld 5 (8Jul Outside2)	Cloud: Cloud/Mesh-Cloud/Mesh	On	1.0000	0.001 m	aligned [0.005 m]

- To join all scans together to form a TRUE 3D representation.
- Basically matching up the names of the scanned targets.
- A least square adjustment calculates the X, Y, Z shift and rotation for each scan.

Registration Media:

- Cyrax targets
- Point Cloud constraints

3D Laser Scanner A:

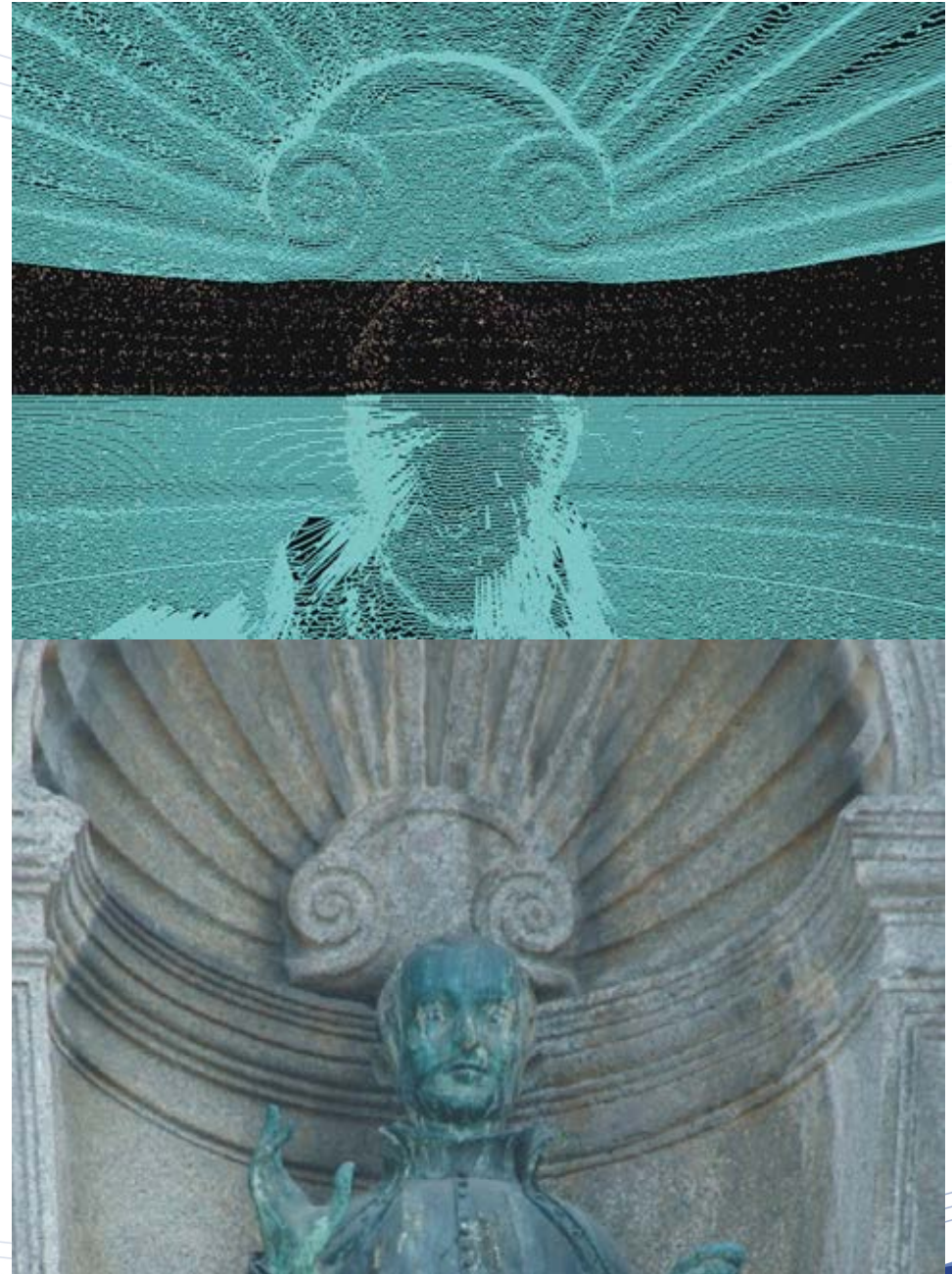
- Number of Scan Worlds: 14
- Total no. of points: about 4.7 B
- Days of Scanning: 7 Days
- Post-Processing Time: 30 Days

3D Laser Scanner B:

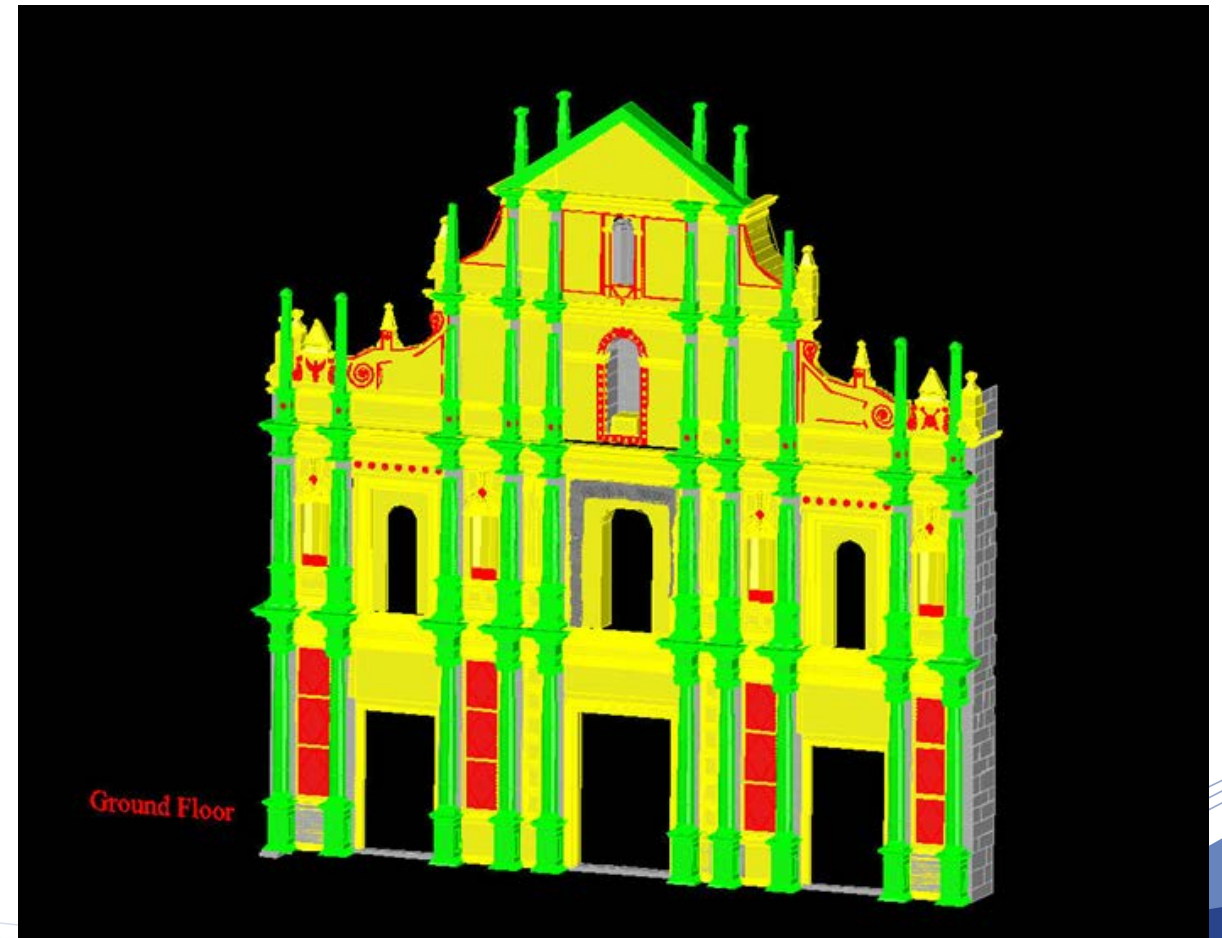
- Number of Scan Worlds: 12
- Total no. of points: about 10 B
- Days of Scanning: 2 Days
- Post-Processing Time: 10 Days

3D Modelling:

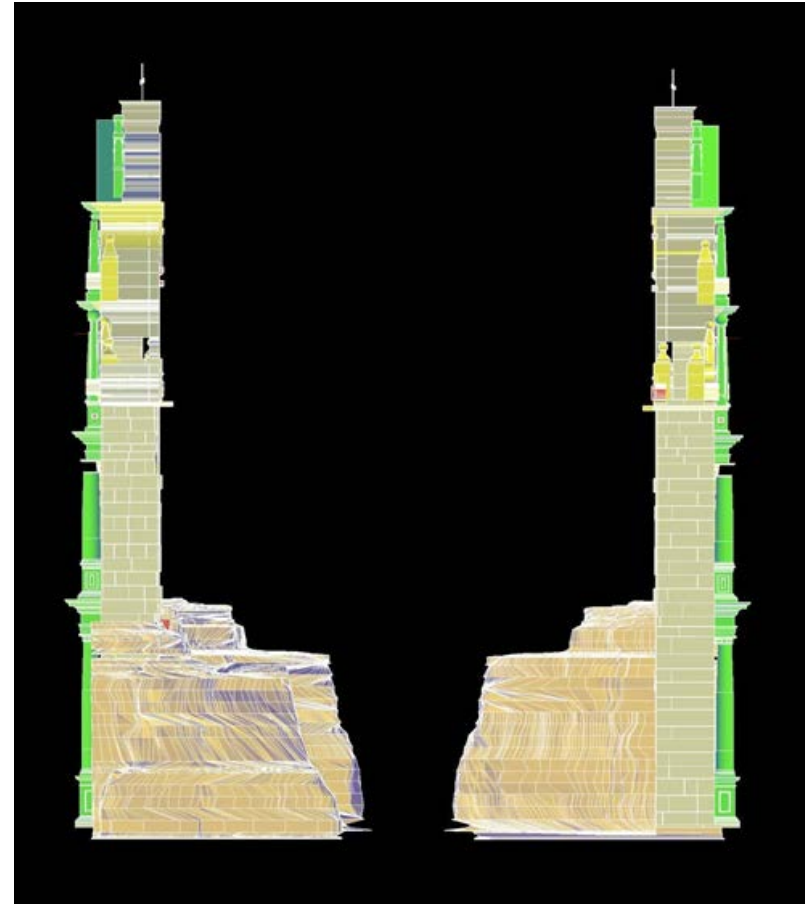
Forming of Horizontal and Vertical Sectional line in 3 millimetre (i.e. 0.003 metre) separation with the sectional alignment parallel to wall face.



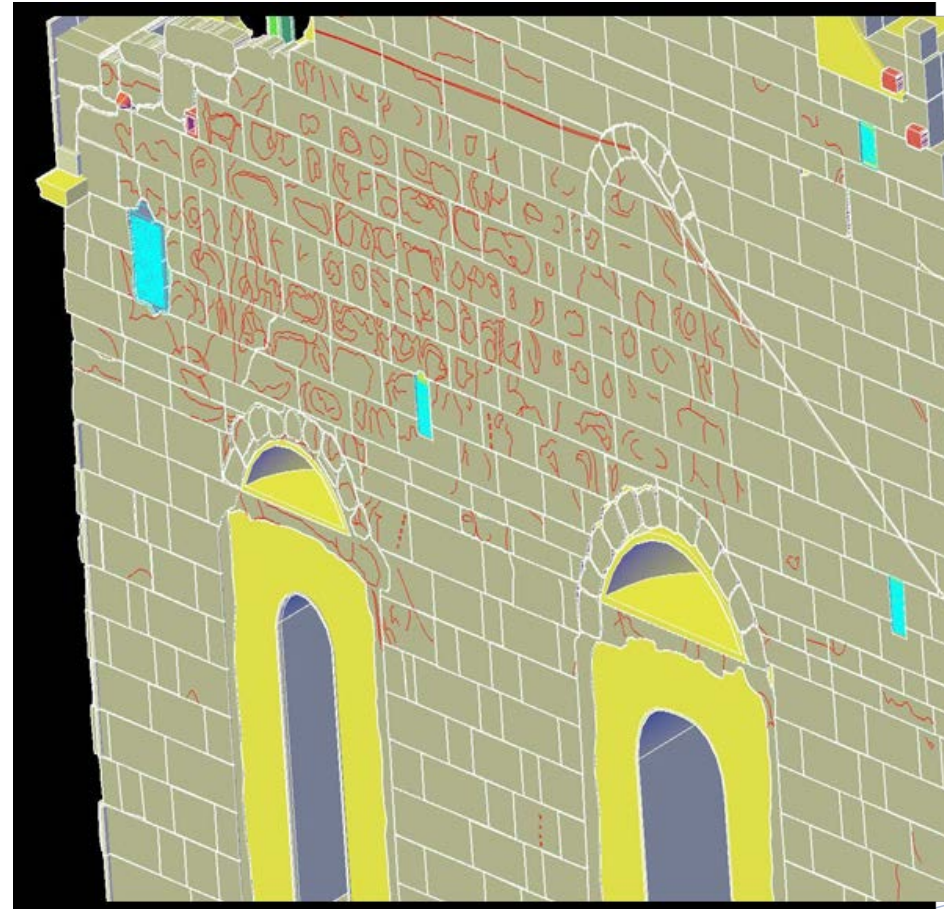
- Building the model.



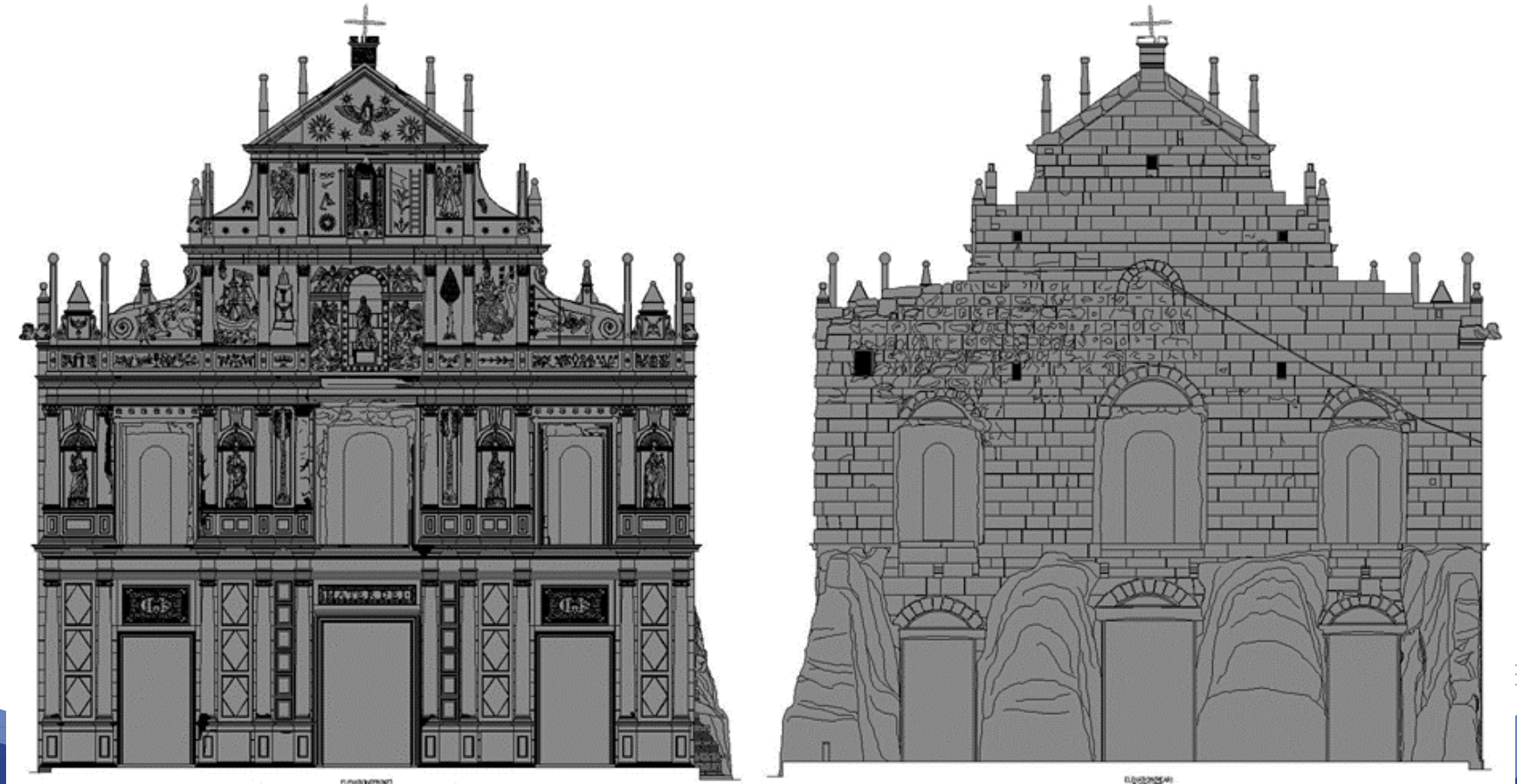
- 3D modelling (Wire- frame presentation)
- Front Elevation (Conceptual presentation)
- Rear Elevation (Conceptual presentation)
- Side Elevations (Conceptual presentation)



- 3D modelling of columns, wall face and defects (Conceptual presentation)



- Elevation drawings.



- Front Elevation-Details.



12.2 Verification of BIM Model by 360 spherical photos

Mobile Scanner

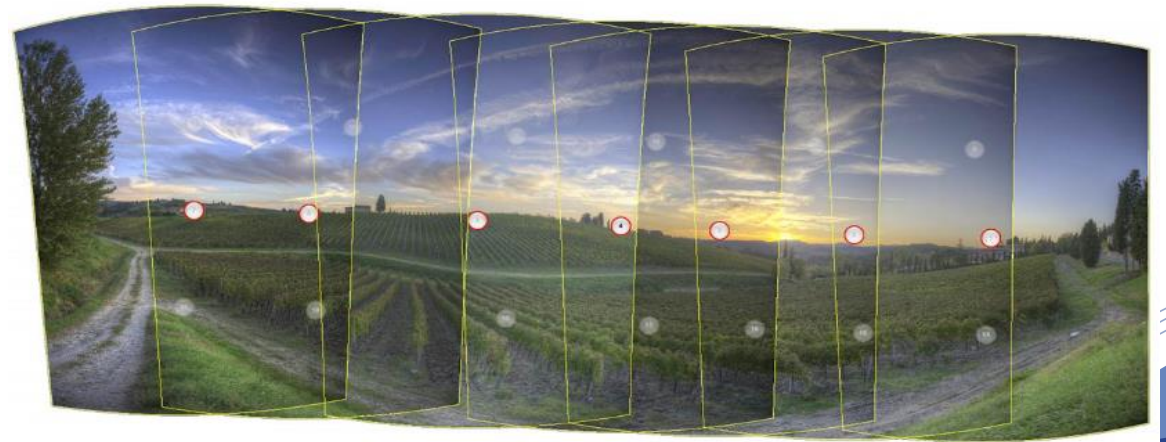


UAV Devices

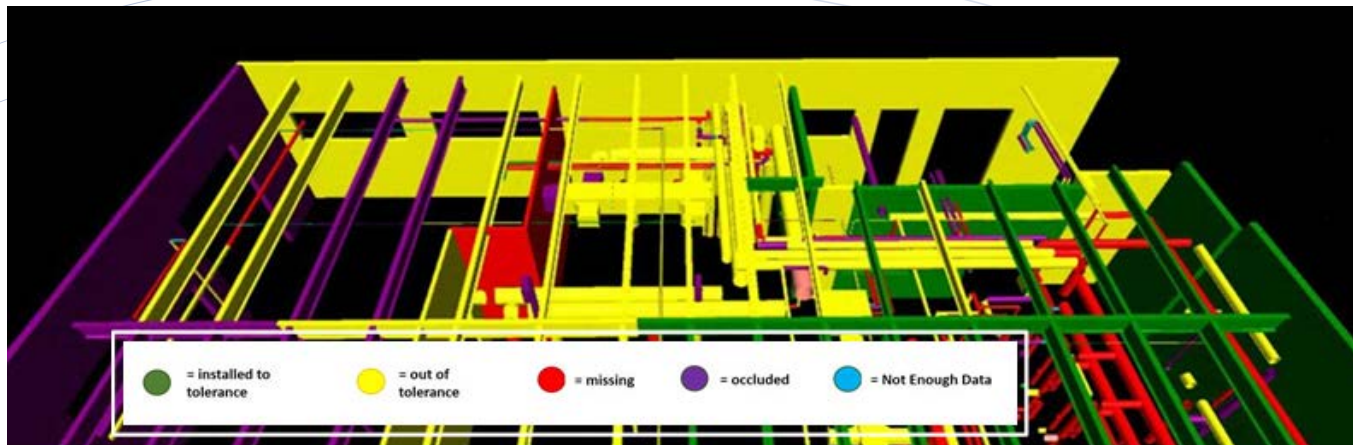




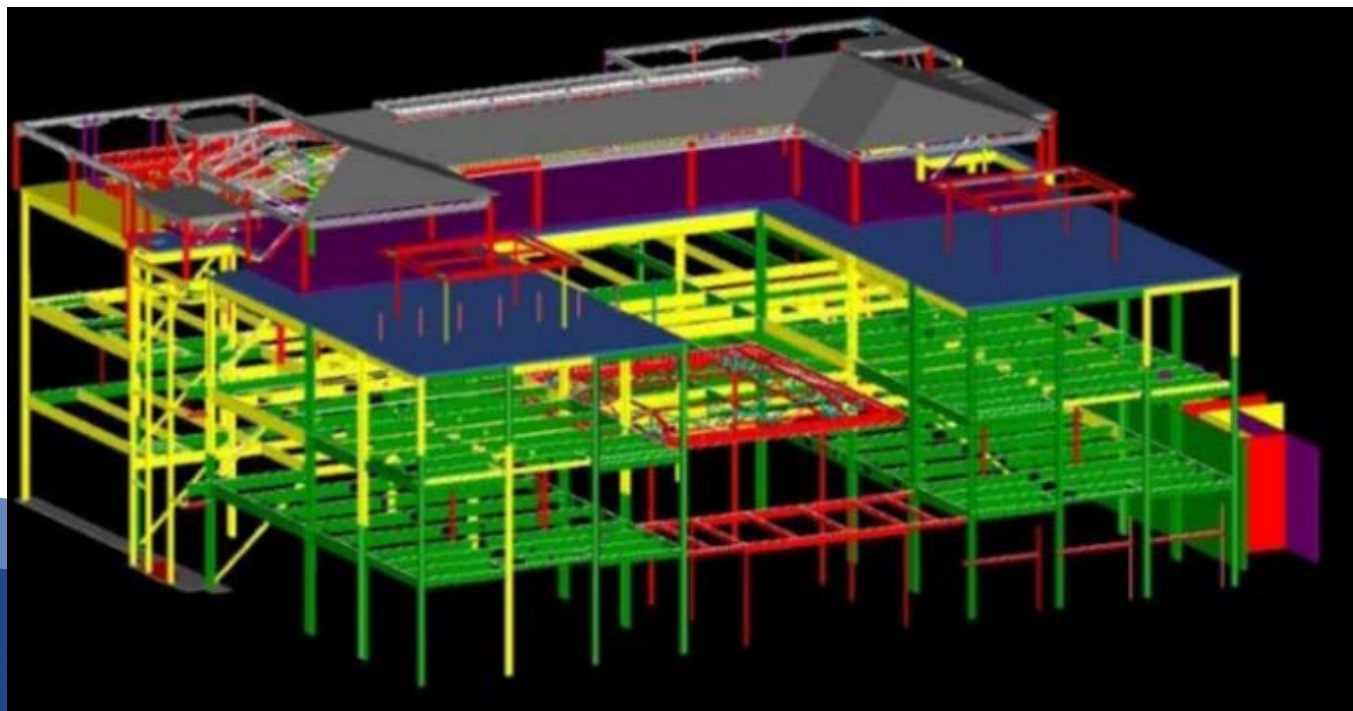
Point Cloud



Verification



Verity's "stop light" variance classification gives you a quick overview of construction quality.



Yellow circle = out of tolerance Red circle = missing Green circle = present and in tolerance Purple circle = occluded

Demonstration

BIM Model Construction

for
Existing Buildings